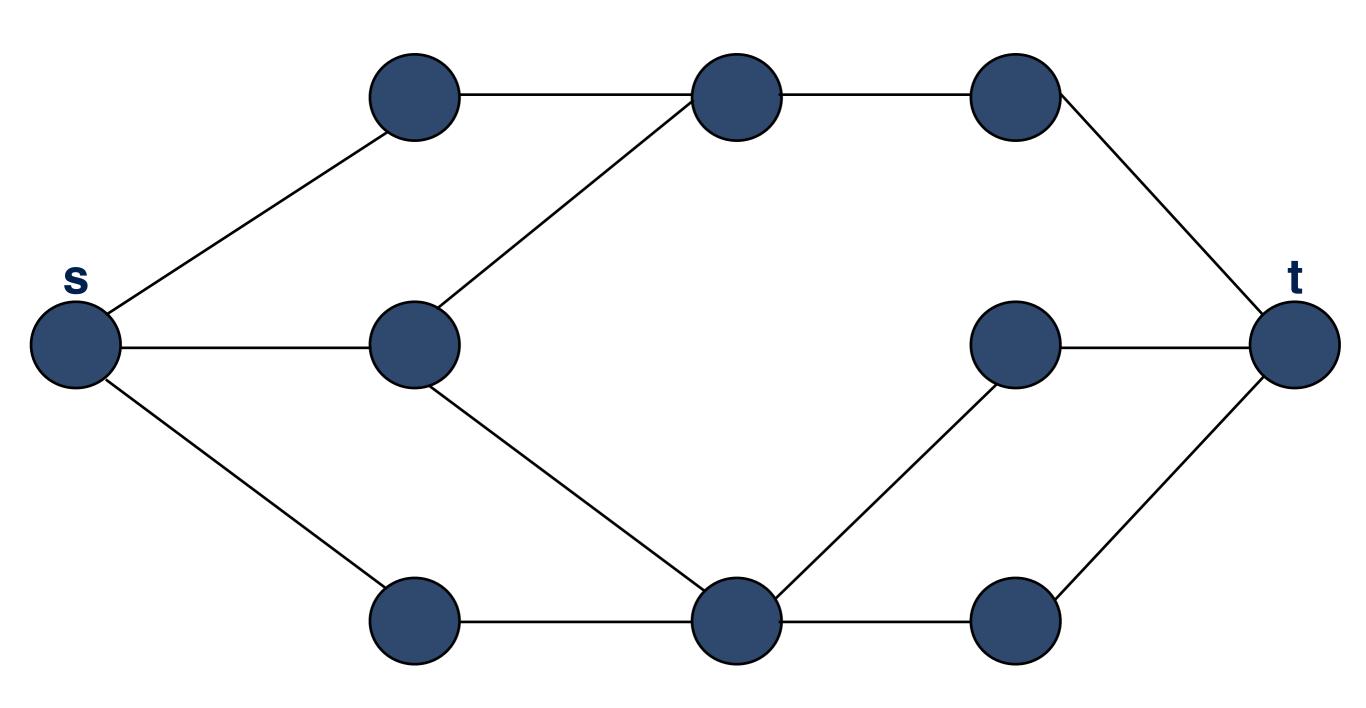
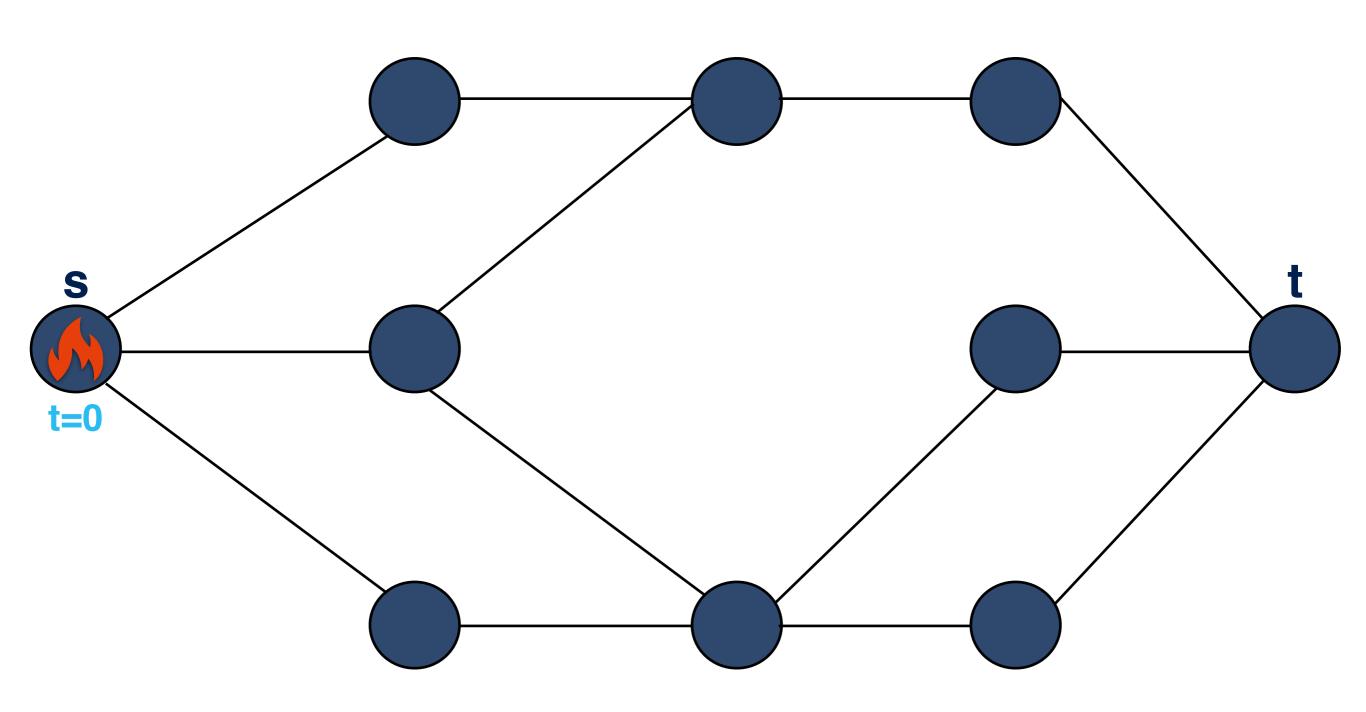
Saving Critical Nodes with Firefighters is FPT

<u>Jayesh Choudhari</u>*, Anirban Dasgupta*, Neeldhara Misra*, M. S. Ramanujan[†]

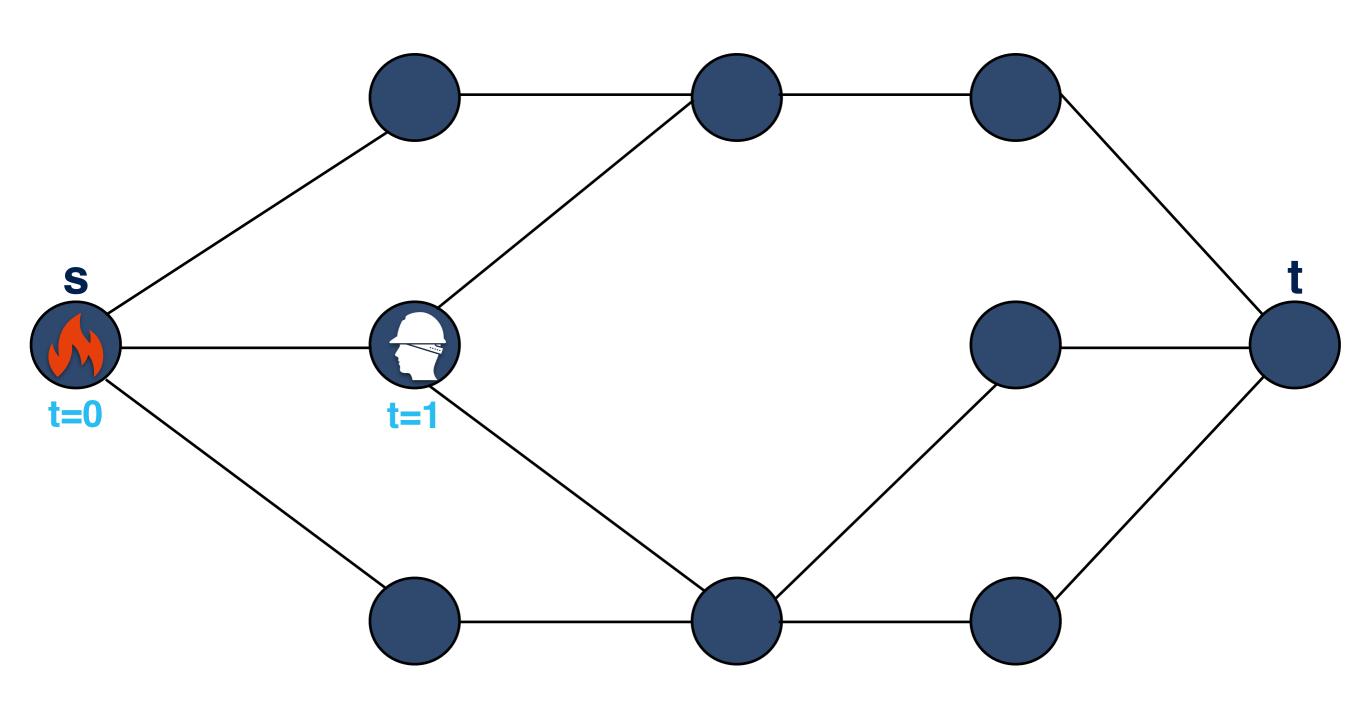
* - IIT Gandhinagar, † - University of Vienna

Firefighting



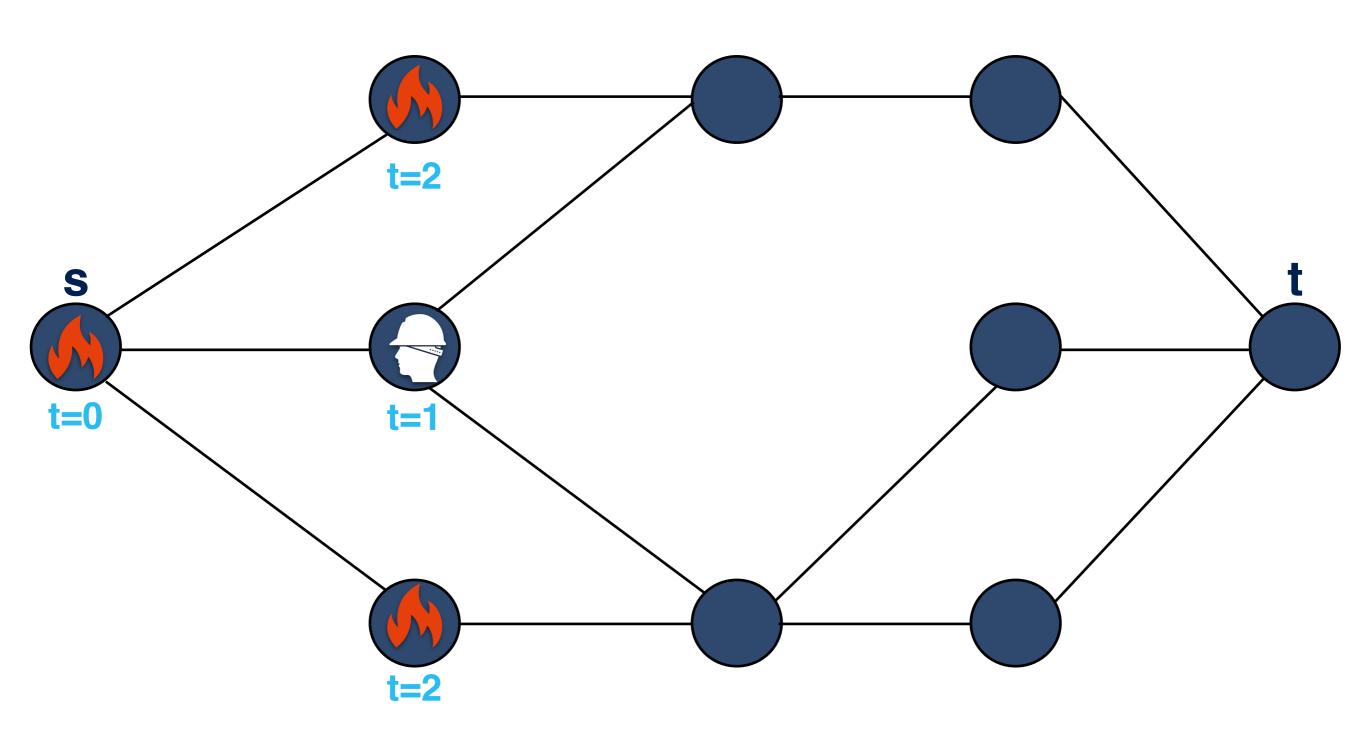






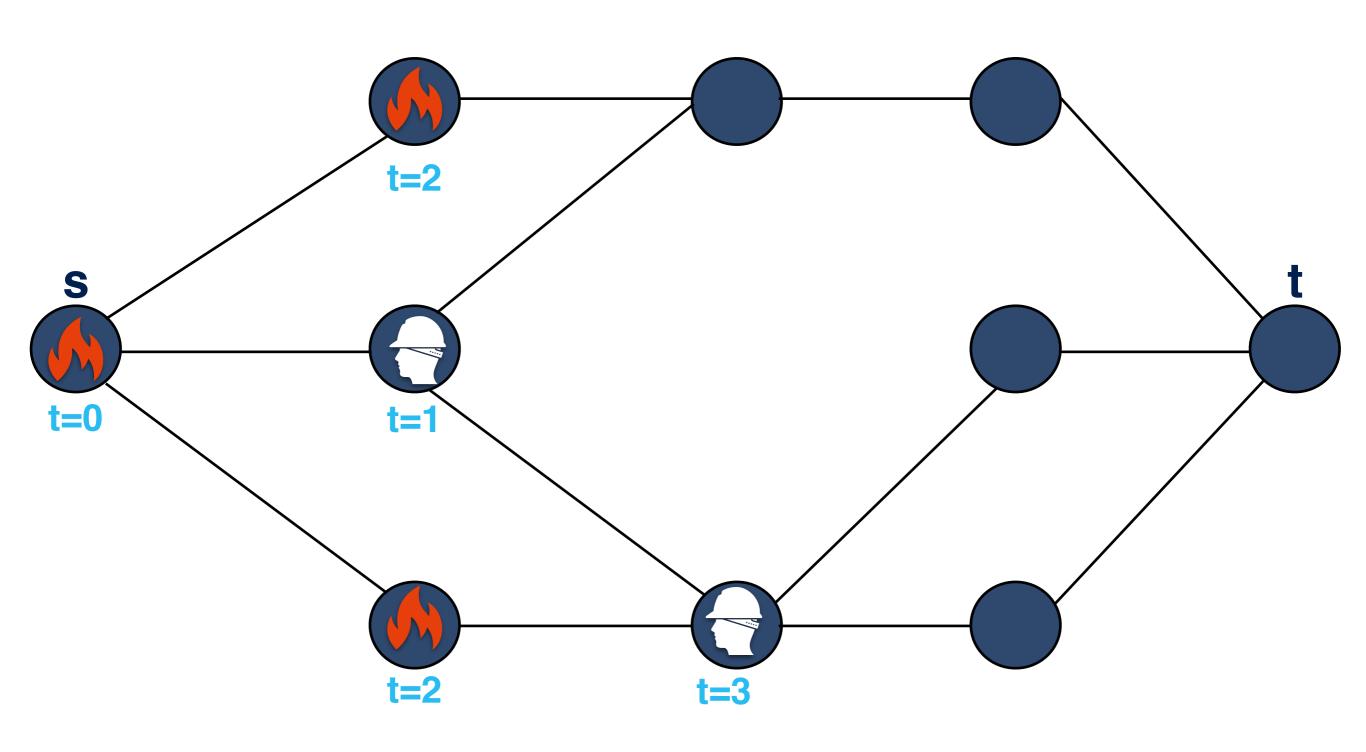






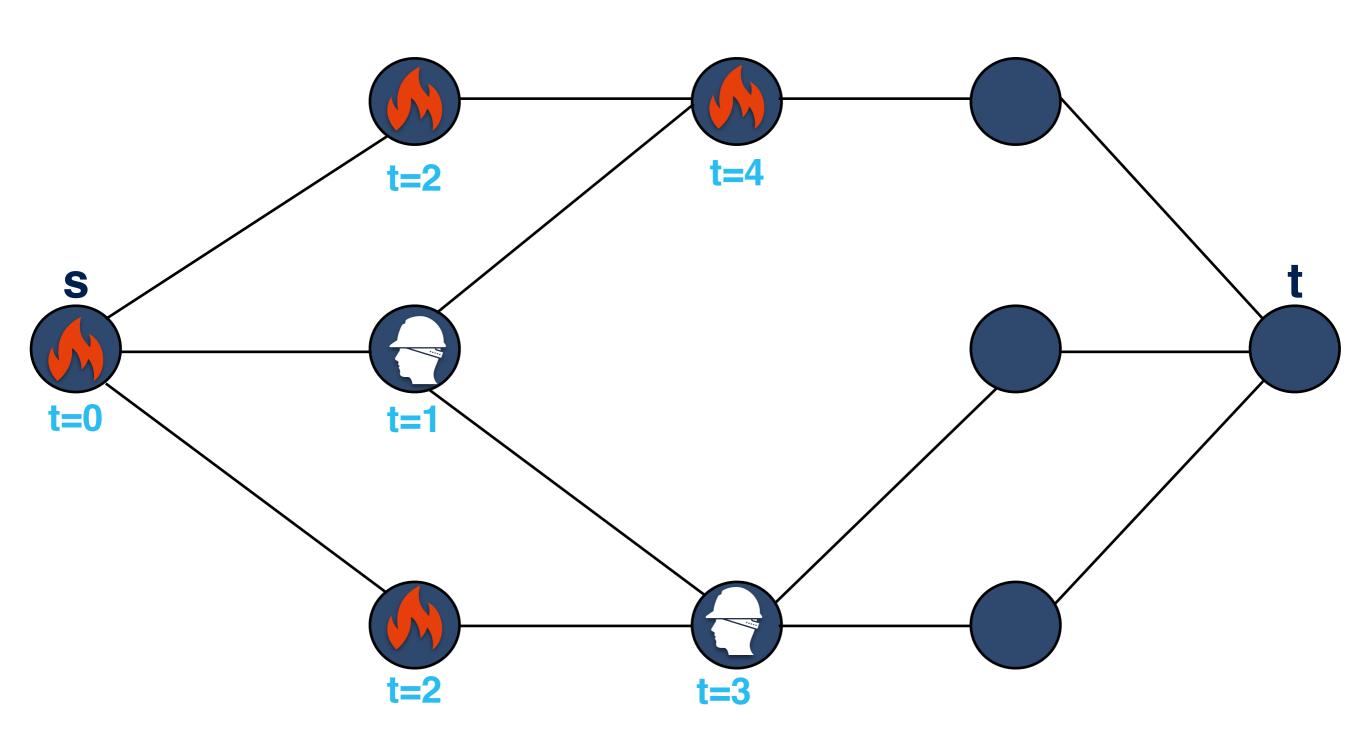






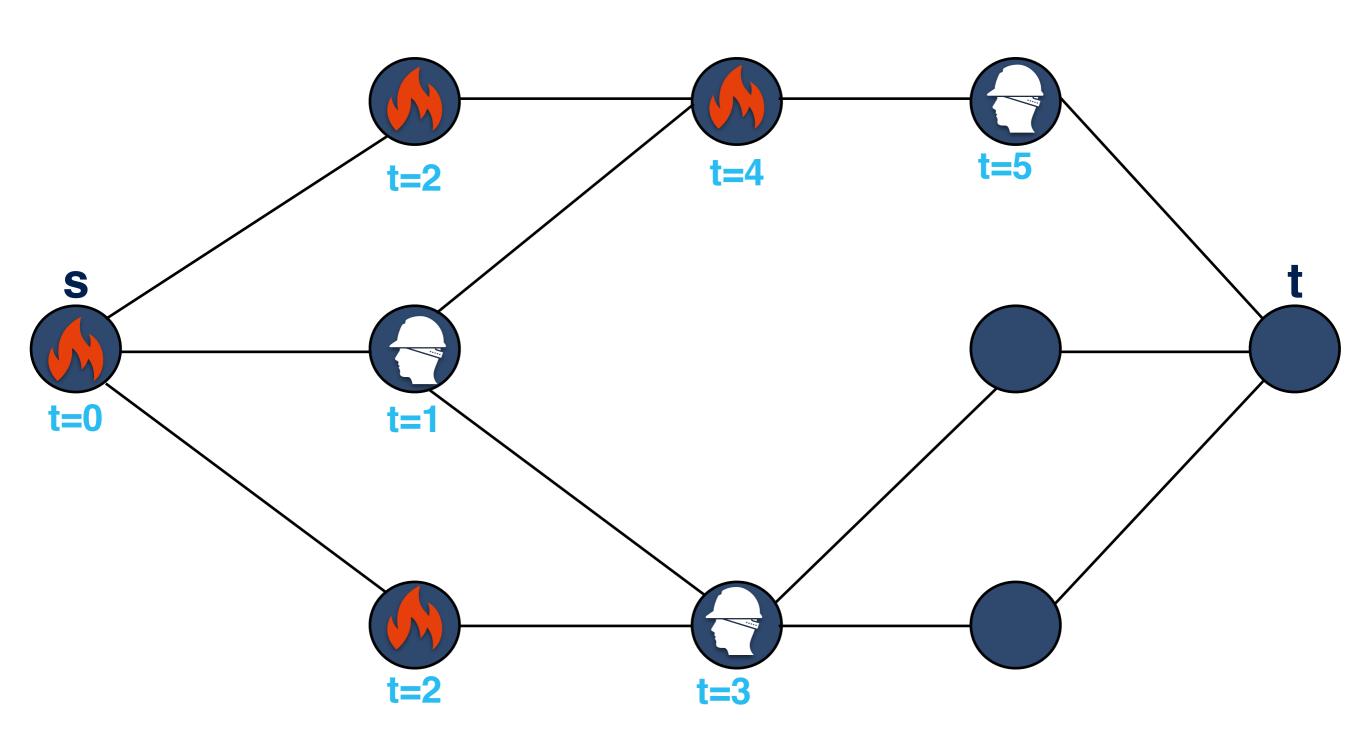






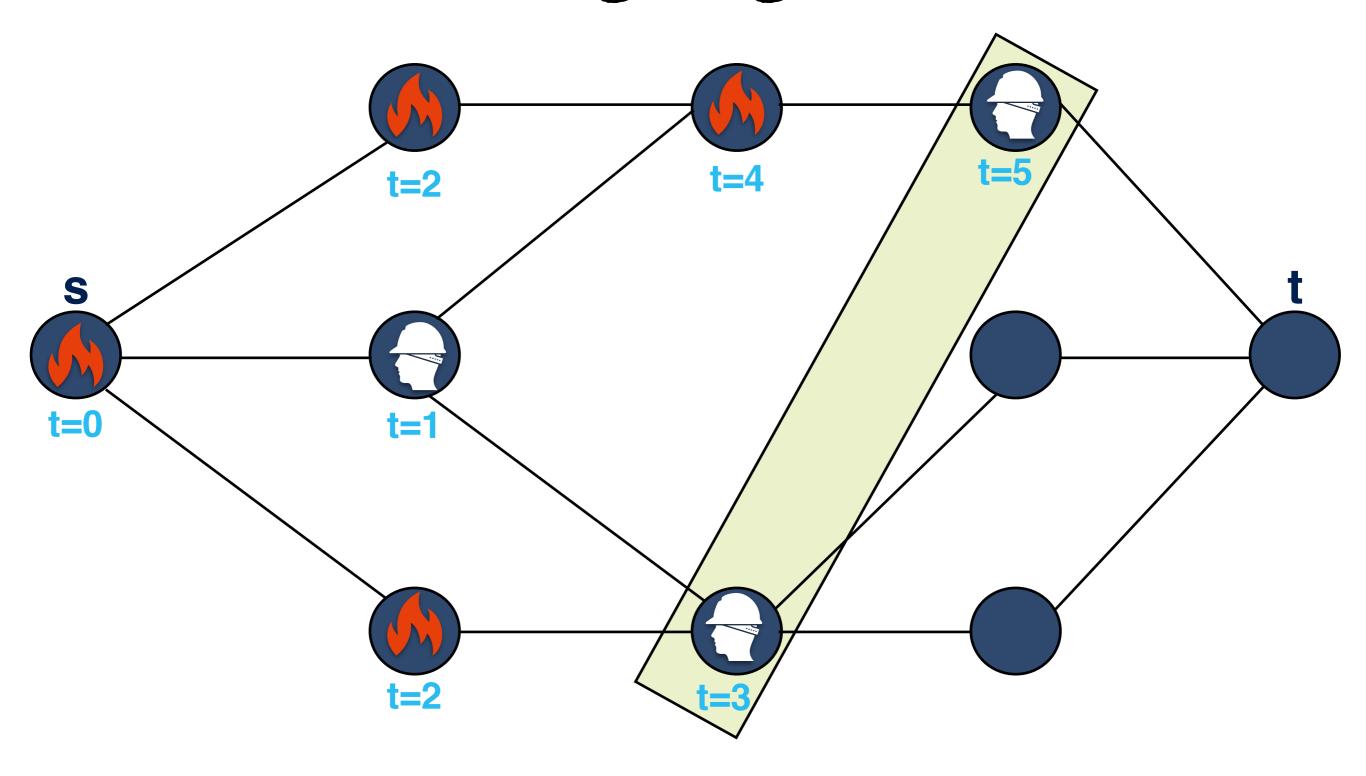






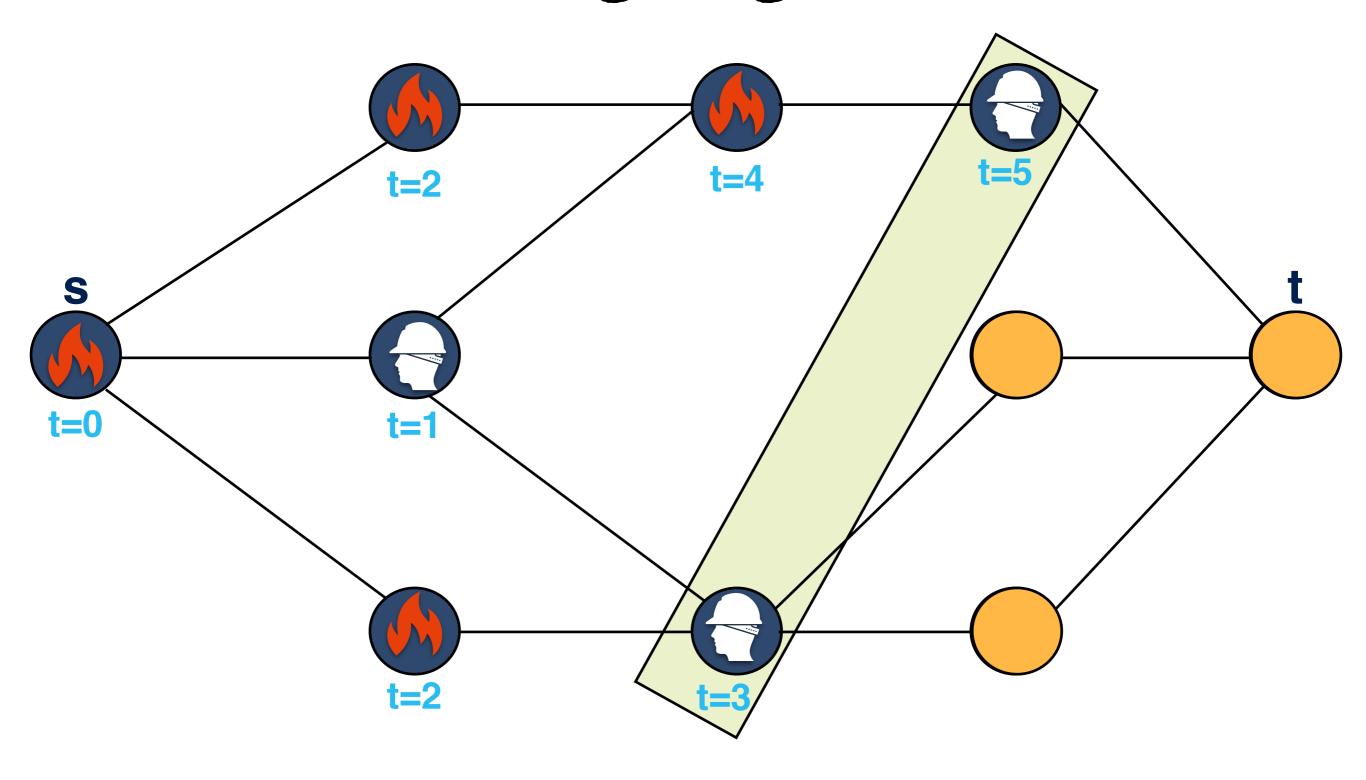


















Objectives of the Firefighting Problem

- Maximising the number of saved vertices [Cai, Verbin, and Yang, 08]
- Minimising the number of burned vertices [Cai, Verbin, and Yang, 08, Finbow, Hartnell, et. al., 09]
- Minimising the number of rounds, minimising the number of firefighters per round [Anshelevich, Chakrabarty, et. al., 09]
- Saving a specific set of vertices [King, MacGillivray, 09]

Saving a Critical Set (SACS)

SACS:

Input:An undirected *n*-vertex graph G, a vertex s, a subset $C \subseteq V(G) \setminus \{s\}$, and an integer k.

Question:Is there a valid k-step strategy that saves C when a fire breaks out at s?

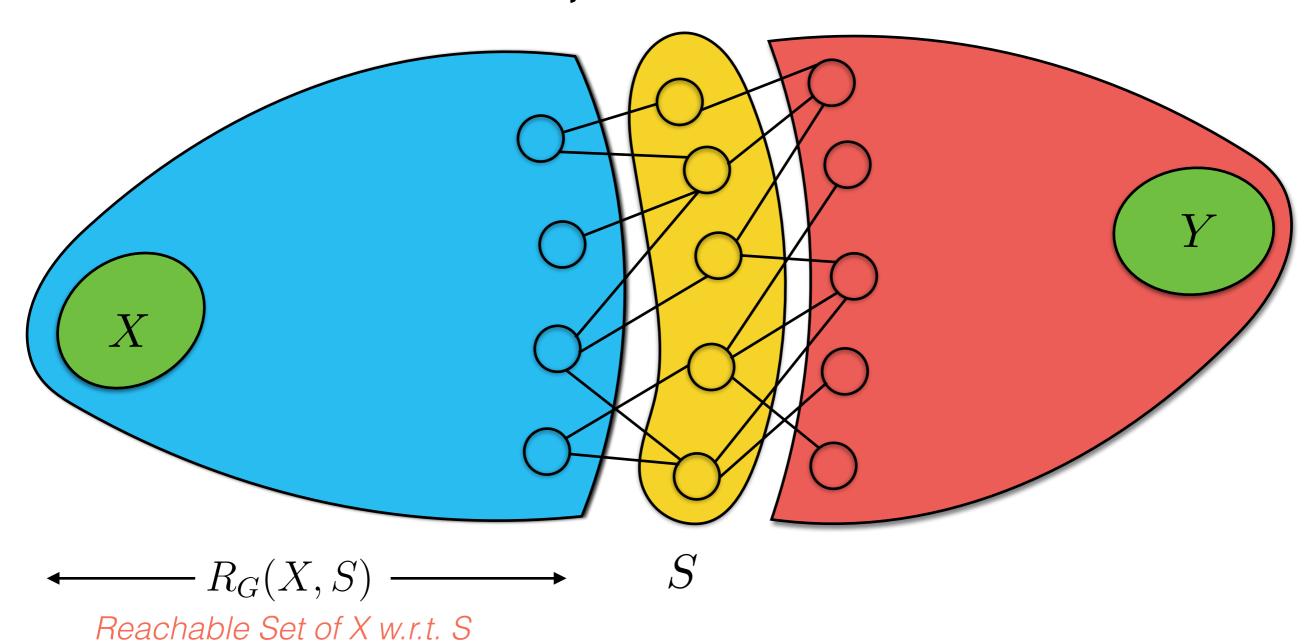
Basic Definitions

Fixed-Parameter Tractability

Definition: A parameterization of a decision problem is a function that assigns an integer parameter k to each input instance I.

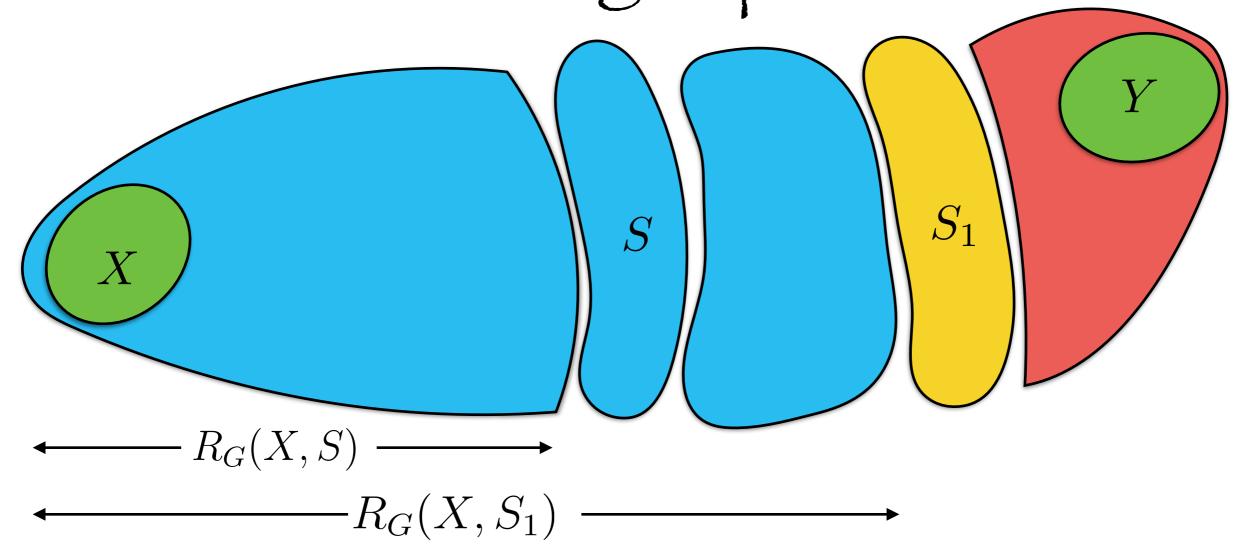
Definition: A parameterized problem is fixed-parameter tractable (FPT) if there is an f(k)n^c time algorithm for some constant c.

Separators



A subset $S \subseteq V(G) \setminus (X \cup Y)$ is said to be a separator if $R_G(X, S) \cap Y = \phi$ or in other words there is no path from X to Y in $G \setminus S$

Dominating Separators

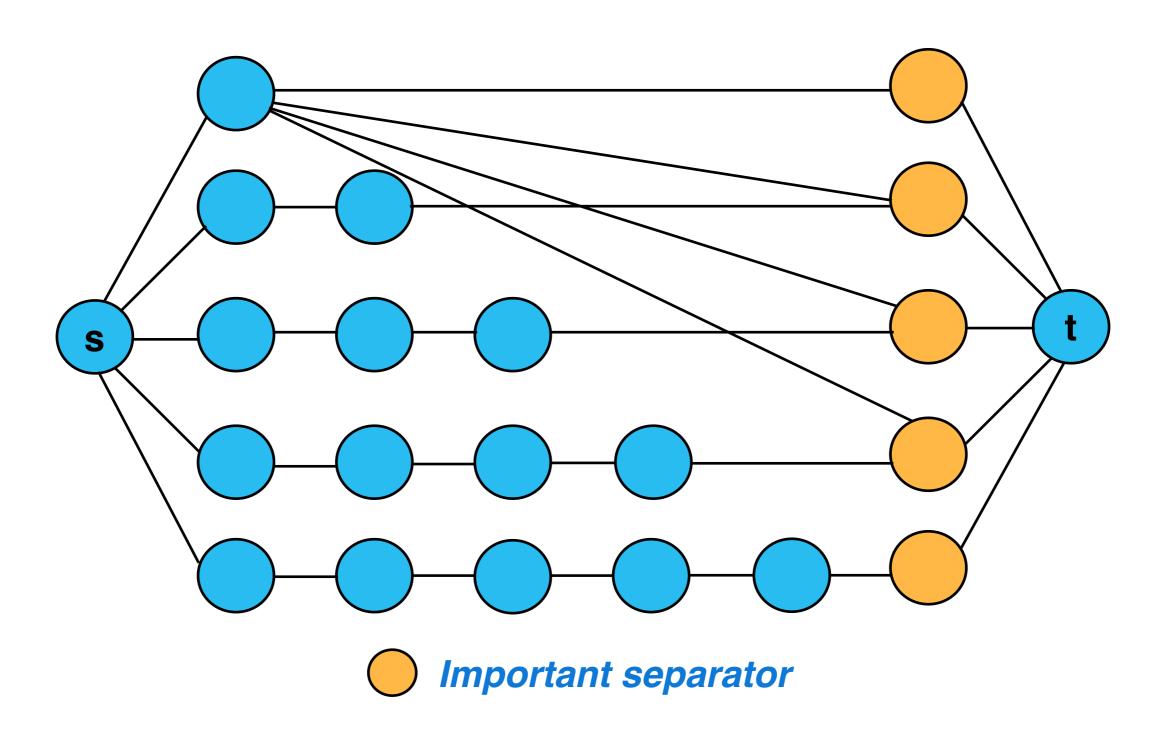


A separator S_1 is said to be dominating w.r.t separator S

- $\bullet |S_1| \le |S|$
- $R_G(X,S) \subseteq R_G(X,S_1)$

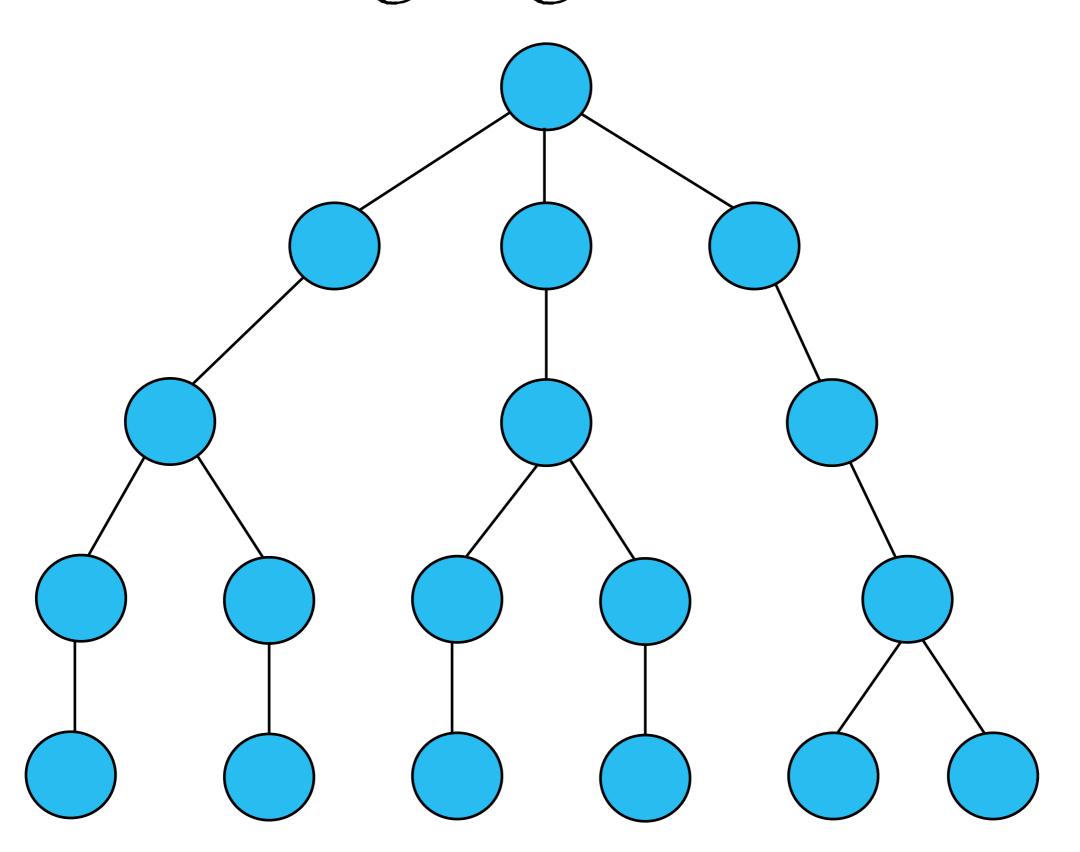
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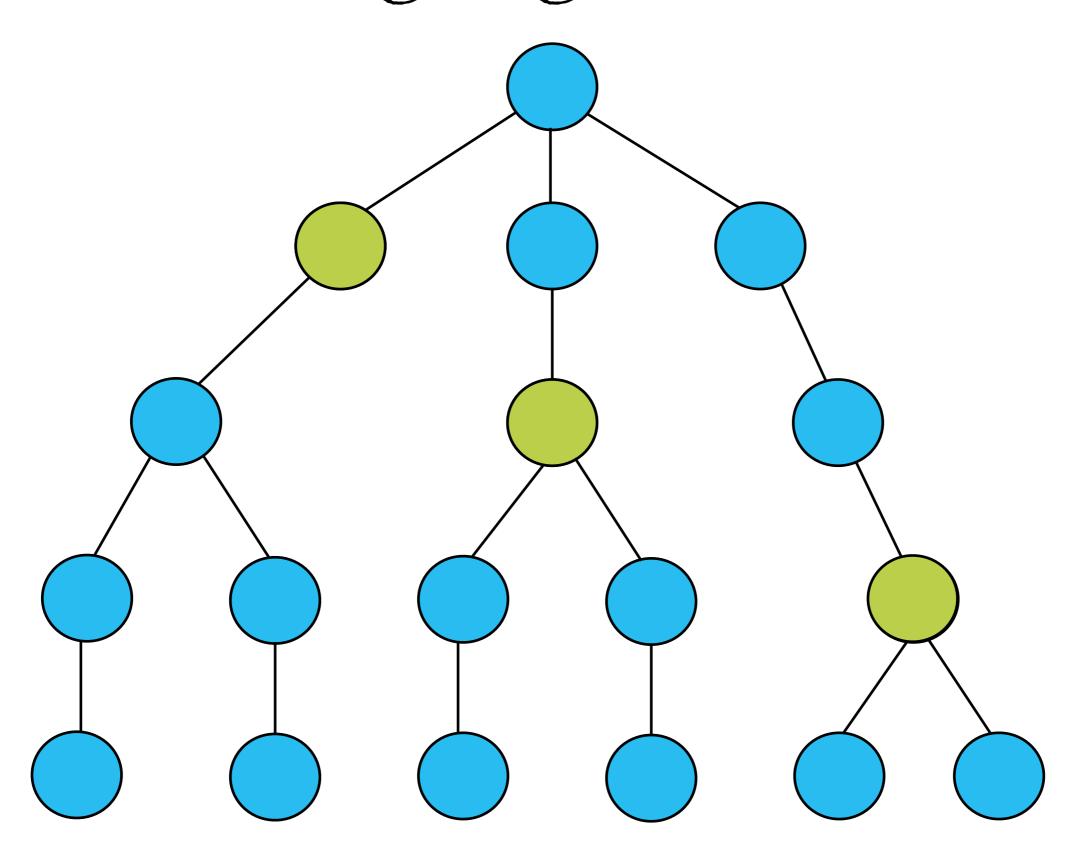


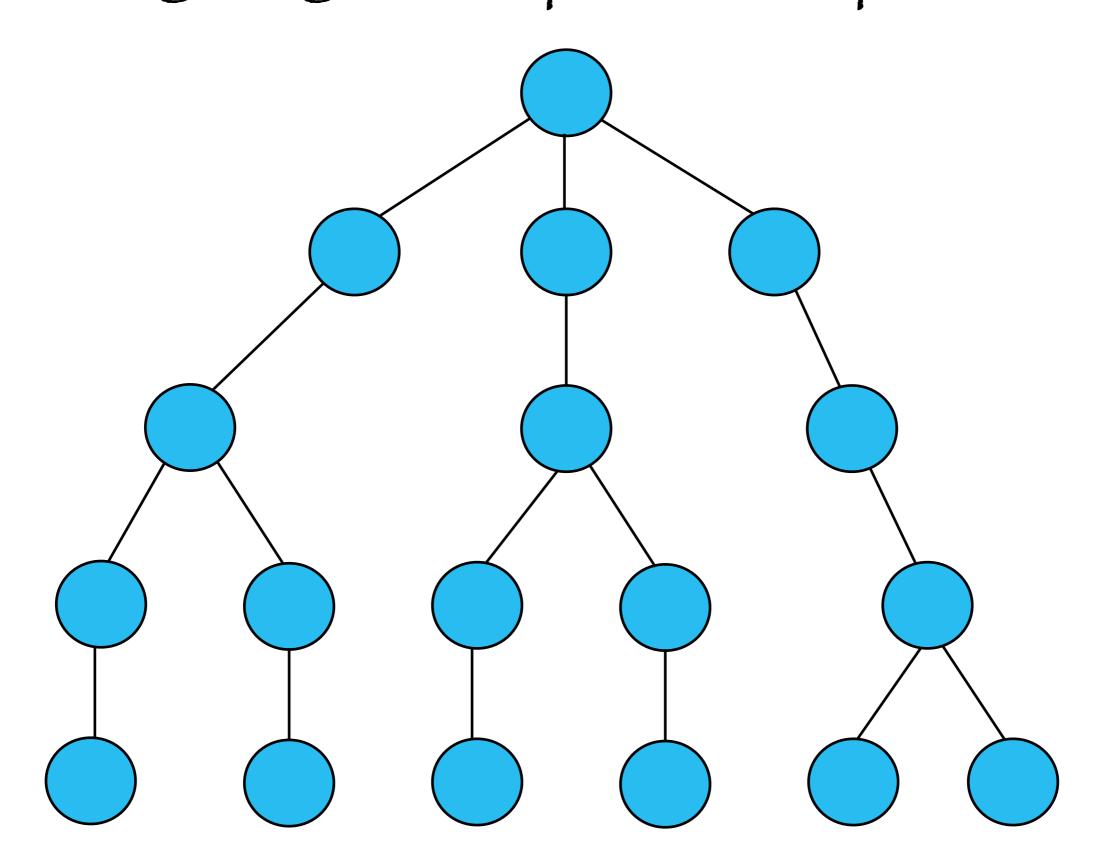
Firefighting on Trees

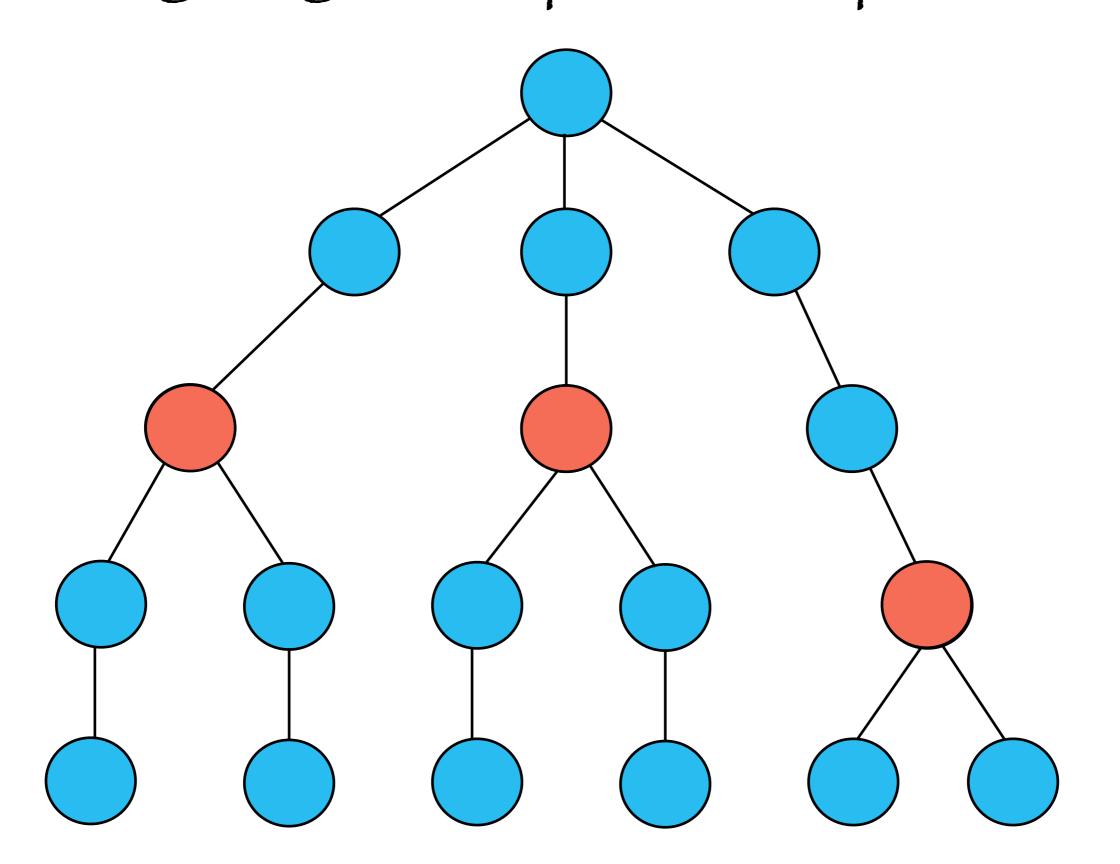
Firefighting on Trees



Firefighting on Trees







Theorem: (Marx, 2011)

For trees, there are at most 4^k important separators of size at most k.

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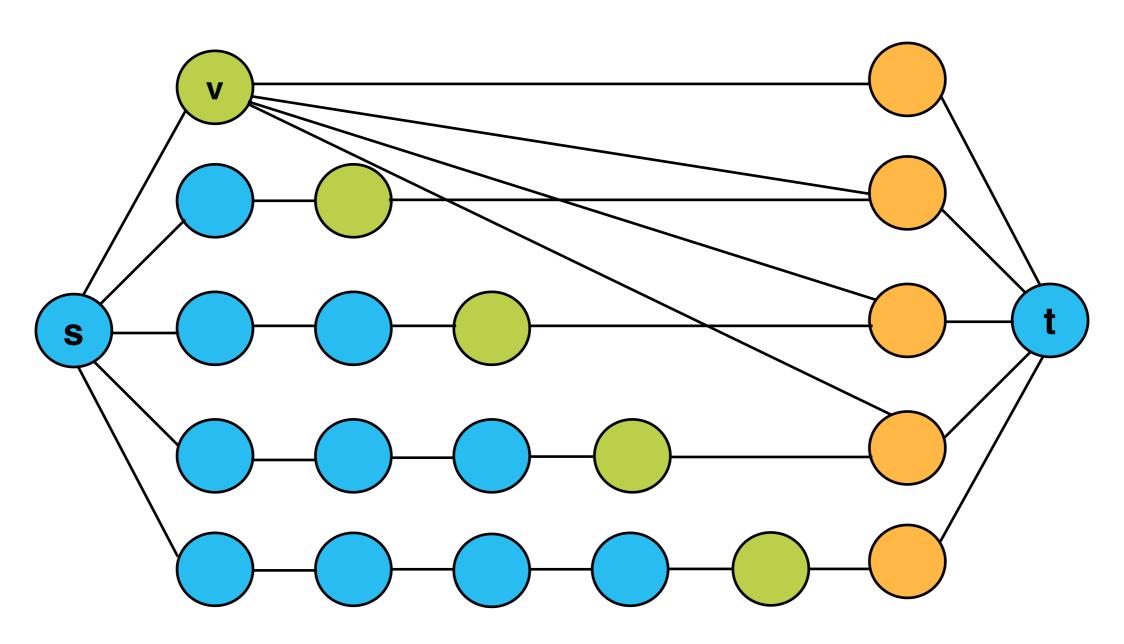
For trees, there are at most 4^k important separators of size at most k.

SACS on trees takes time $O^*(4^k)$

Firefighting on Graphs

Important separators do not suffice !!!

Important separators do not suffice !!!



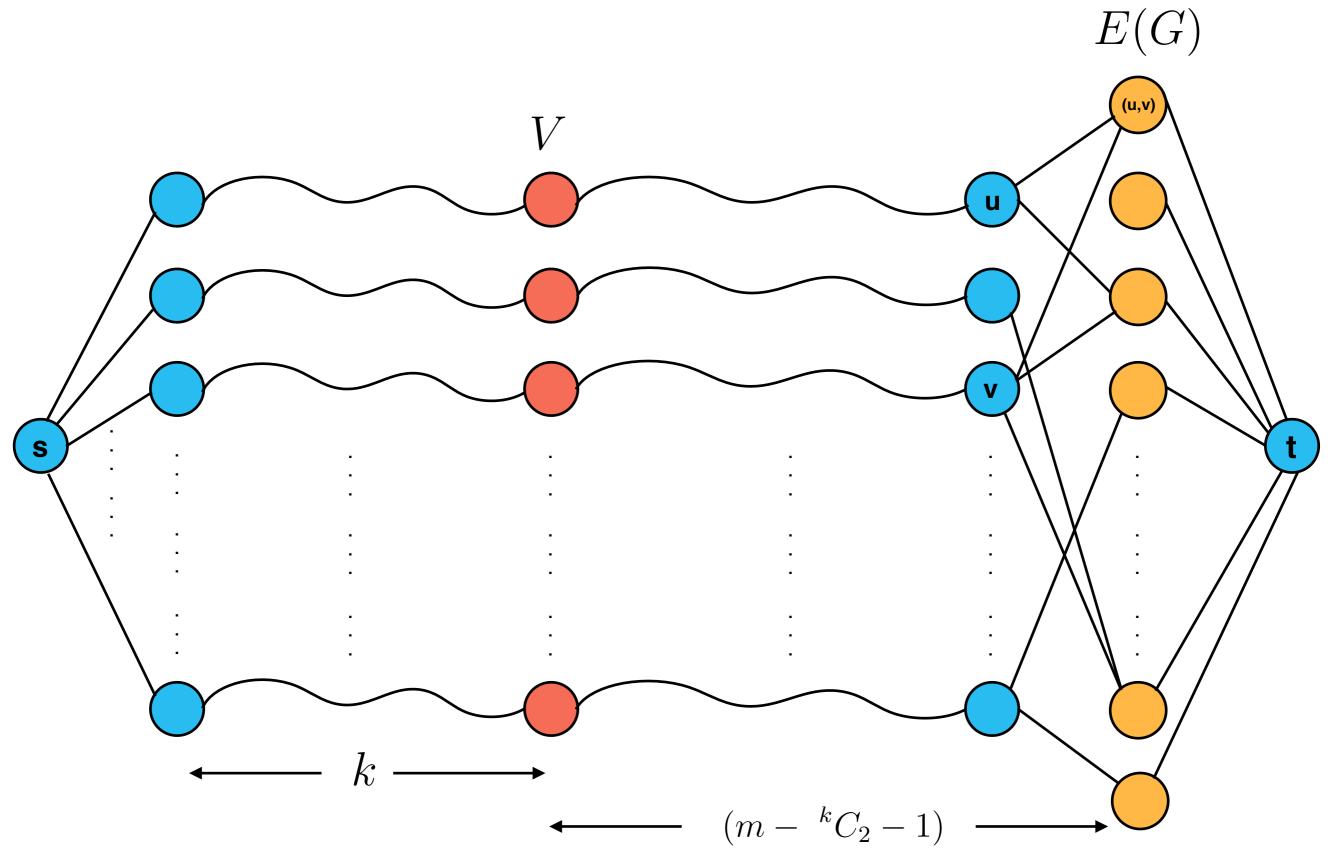




Saving a Critical Set - NPC

Saving A Critical Set (SACS) with critical set of size 1 is a YES-instance if and only if k-CLIQUE is an YES-instance

Saving a Critical Set - NPC



Saving a Critical Set - NPC

SACS with size 1 has a successful strategy with $(k + m - {}^kC_2)$ firefighters in this new graph G' if and only if G has a clique of size k.

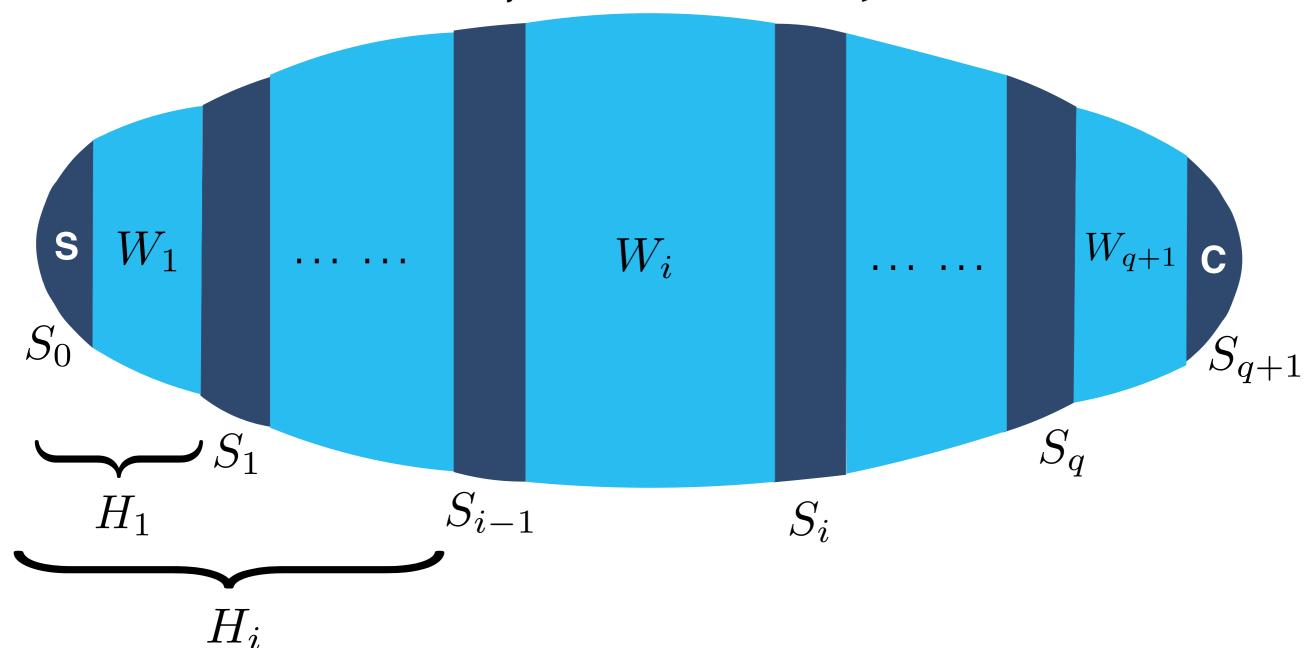
Tight Separator Sequence

Let X, Y be two subset of vertices in graph G. Then, a tight (X, Y)reachability sequence of order k is an ordered collection $H = \{H_1, H_2, ..., H_q\}$ of sets in V(G) satisfying the following properties:

- 1. $H_1 \subset H_2 \subset \cdots \subset H_q$,
- 2. $|N(H_i)| \leq k, \forall i, 1 \leq i \leq q$
- 3. $S_i = N(H_i), \forall 1 \leq i \leq q \text{ is a minimal } (X, Y) \text{-separator in } G$

[M. S. Ramanujan, 13]

Tight Separator Sequence



There is an algorithm that runs in time $O(kmn^2)$ that either correctly concludes that there is no X-Y separator of size at most k or outputs the required sequence.

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Case-1:
$$q > k$$

Let
$$S = \bigcup_{i=1}^q S_i$$
 $\mathcal{W} = \bigcup_{i=1}^{q+1} W_i$

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Claim: If G admits a tight (s, C)-separator sequence of order q in $G \setminus Y$ where q > k, then there exists a k-step firefighting strategy.

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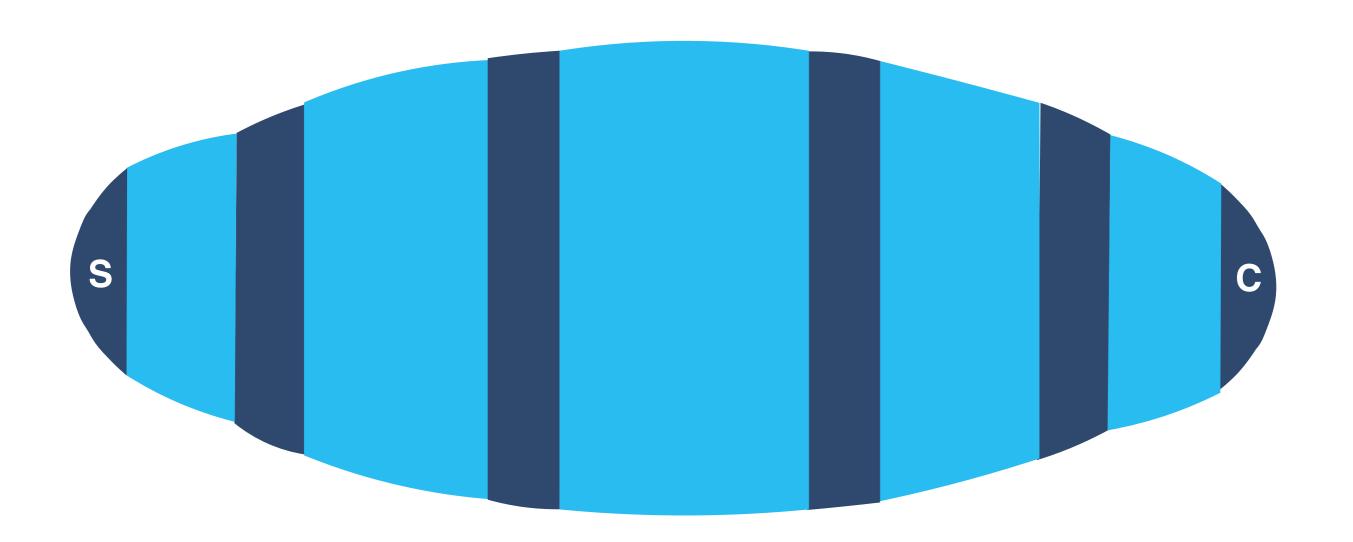
Claim: If G admits a tight (s, C)-separator sequence of order q in $G \setminus Y$ where q > k, then there exists a k-step firefighting strategy.

Place the firefighters on the separator S_q

Case-2: q < k

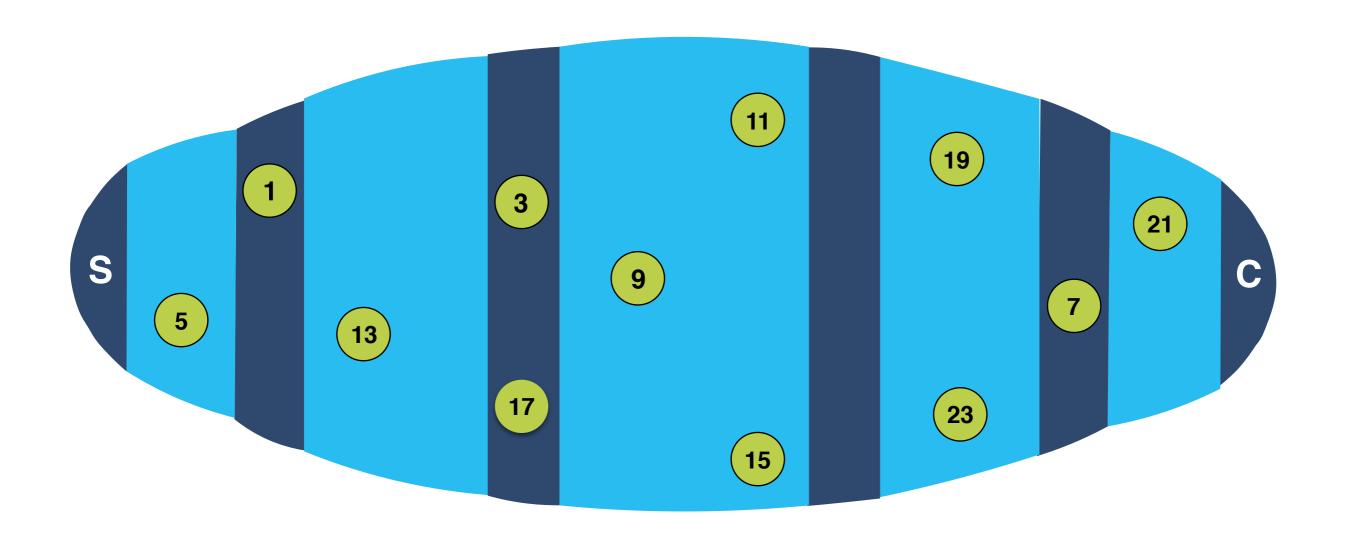
Guess the partition of the timestamps P for a firefighting strategy

For e.g.,
$$P = \{1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23\}$$



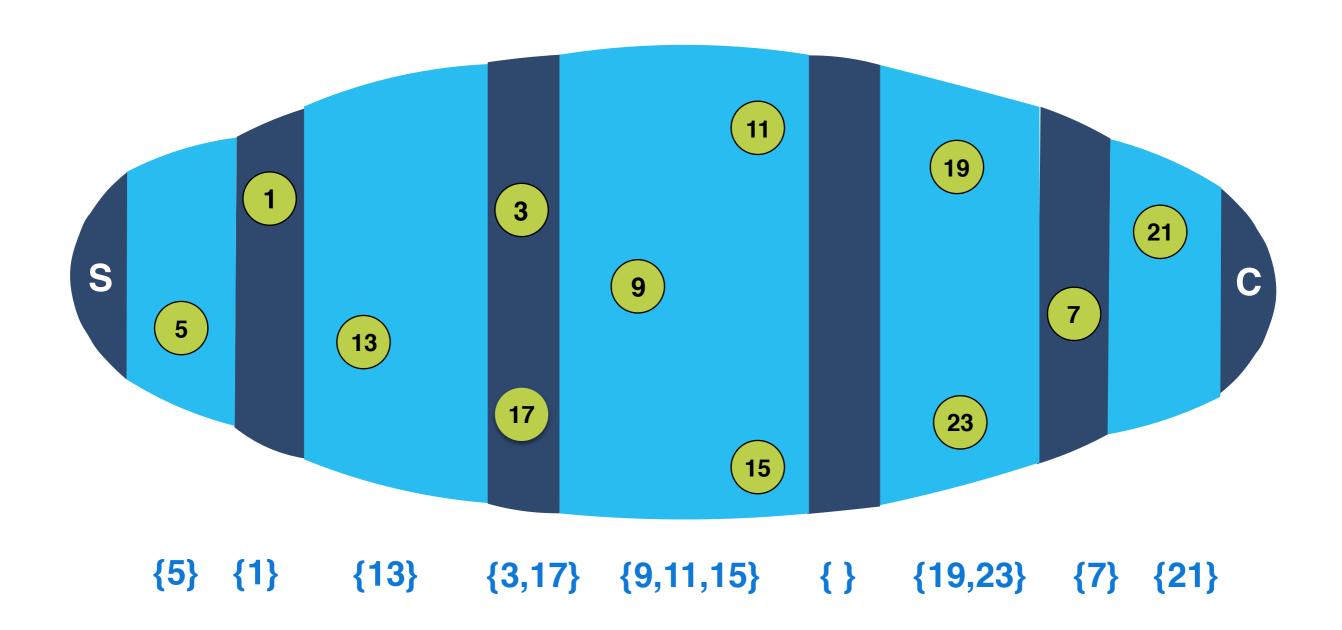
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Partitioned Timestamps

Let

- A_1, A_2, \ldots, A_q denote the timestamps for the nodes inside \mathcal{S} and
- $B_1, B_2, \ldots, B_{q+1}$ denote the timestamps for the nodes inside \mathcal{W} .

$$P = \bigcup_{i=1}^{q} A_i \cup \bigcup_{I=1}^{q+1} B_i$$
$$|P| = p$$

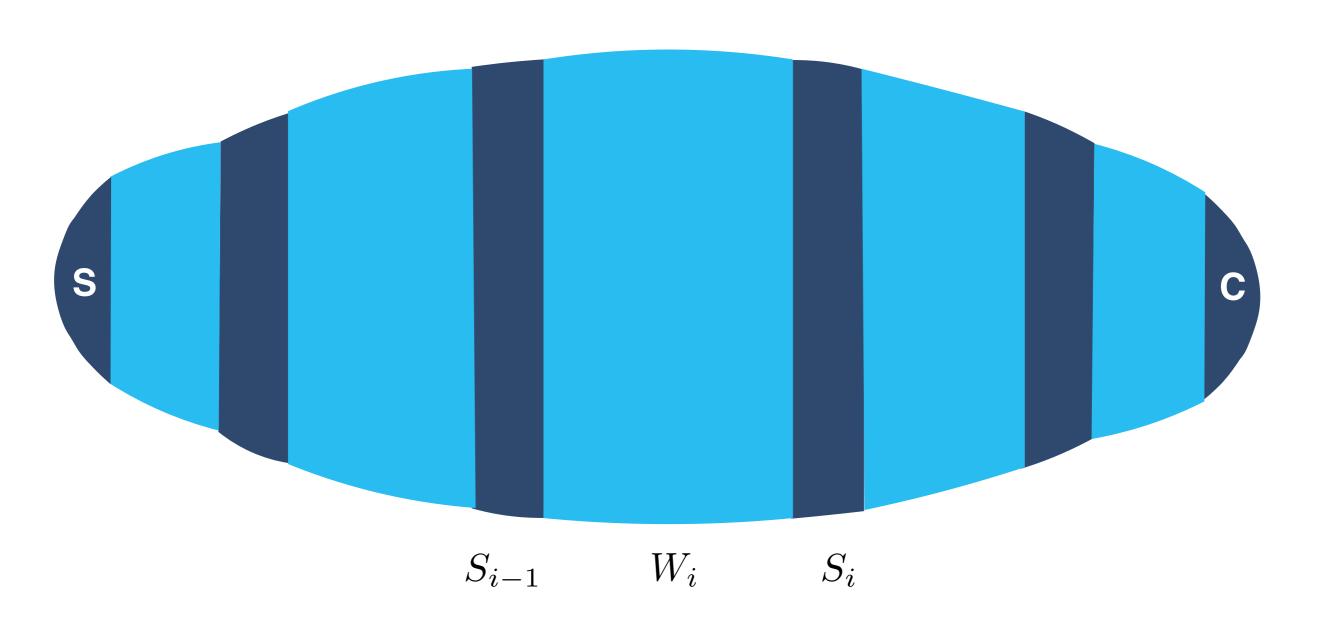
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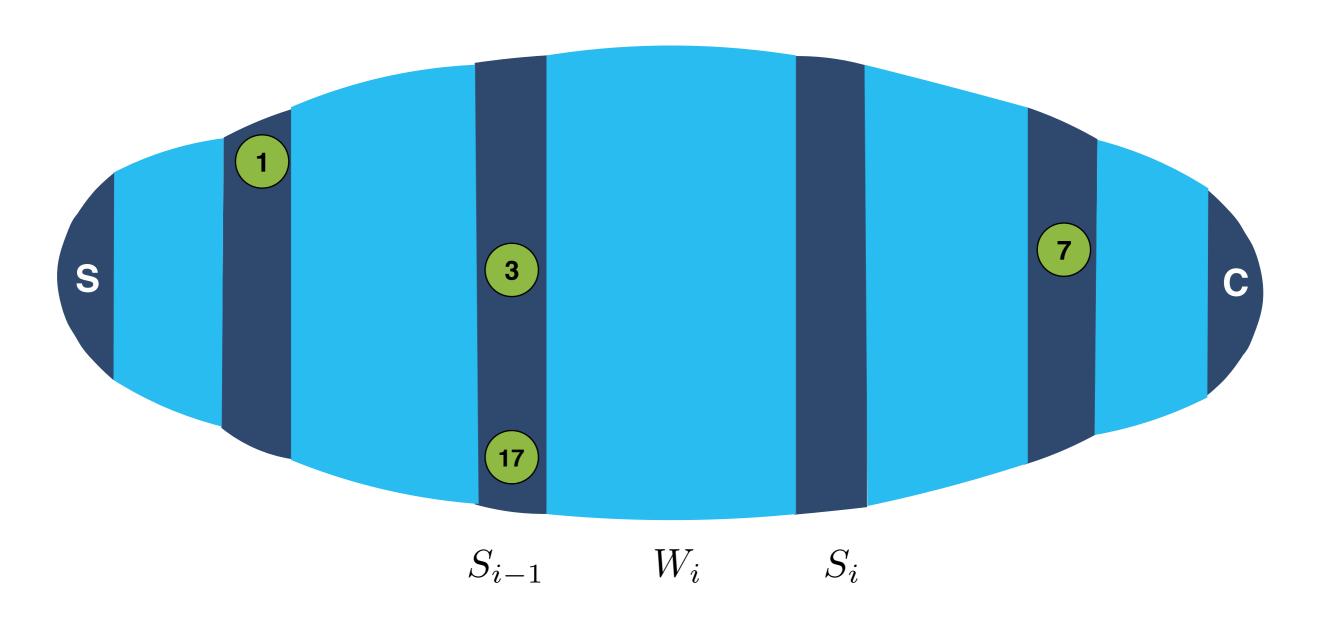
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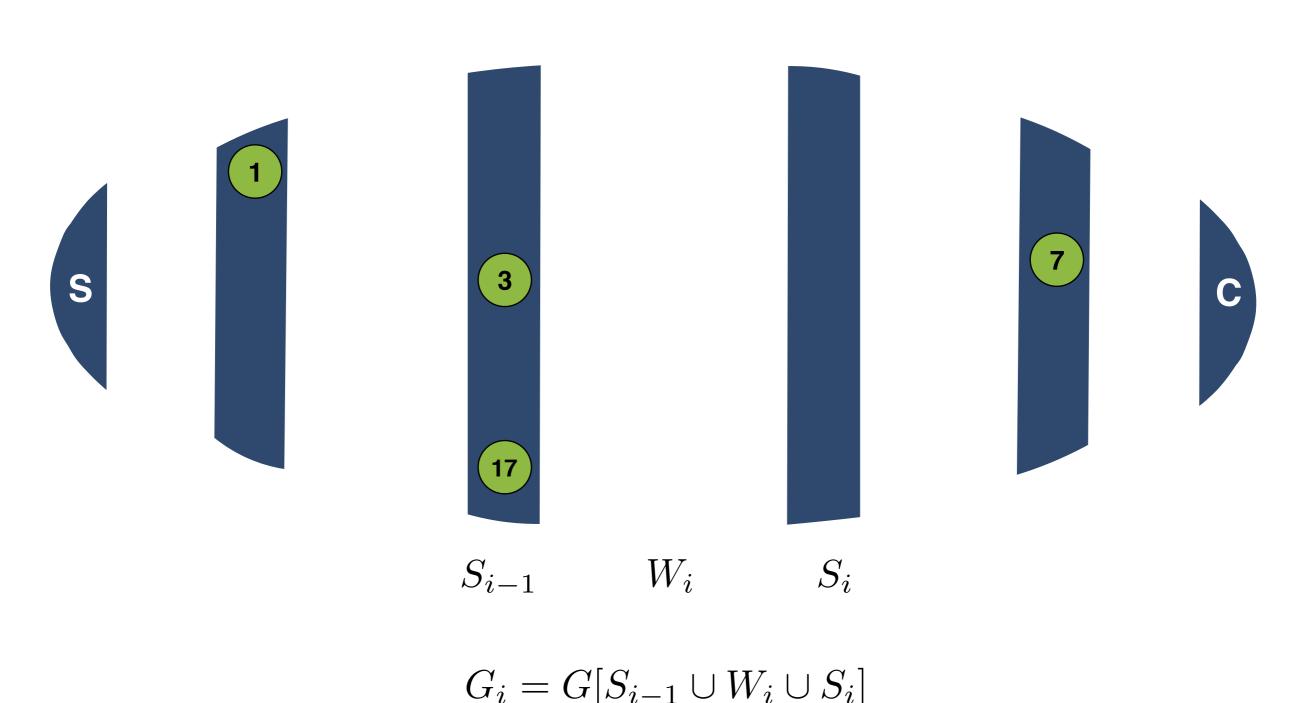
The number of possible partitions = $(2q+1)^p \le (2k+1)^k$

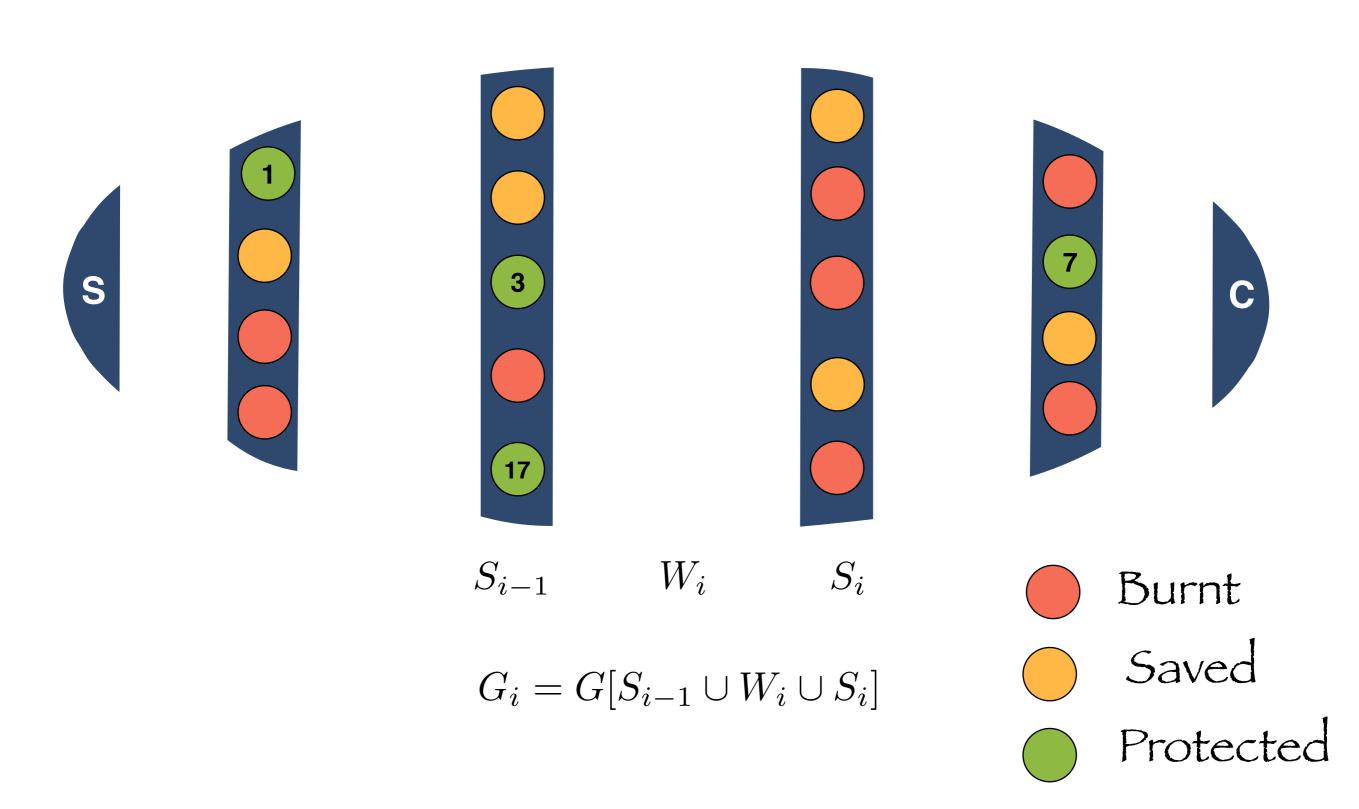


$$G_i = G[S_{i-1} \cup W_i \cup S_i]$$



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$$\mathfrak{L} = (\{\mathfrak{f}\} \times X) \cup (\{\mathfrak{b}\} \times [2k]_E) \cup \{\mathfrak{p}\}$$

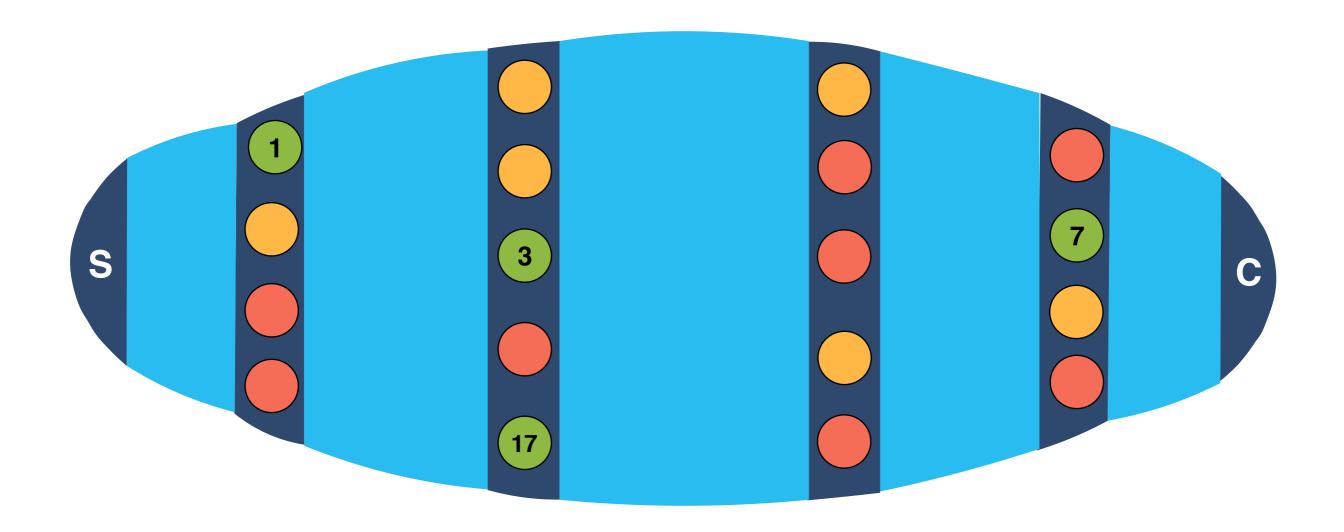
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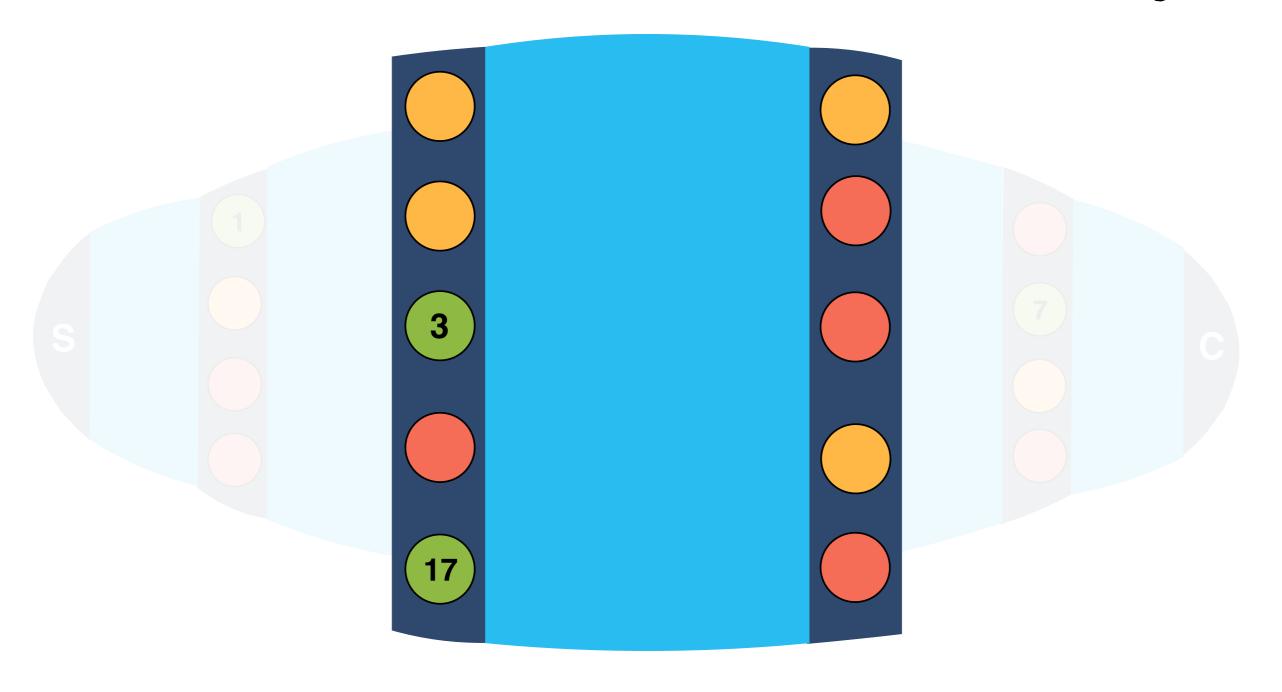
$$\mathfrak{L}_{\mathfrak{h}}(v) = \begin{cases} (\mathfrak{f}, t) & \text{if } \mathfrak{h}(t) = v, \\ (\mathfrak{b}, t) & \text{if } t \text{ is the earliest timestep at which } v \text{ burns,} \\ \mathfrak{p} & \text{if } v \text{ is not reachable from } s \text{ in } G \setminus (\{\mathfrak{h}(i) \mid i \in [2k]_O\}) \end{cases}$$

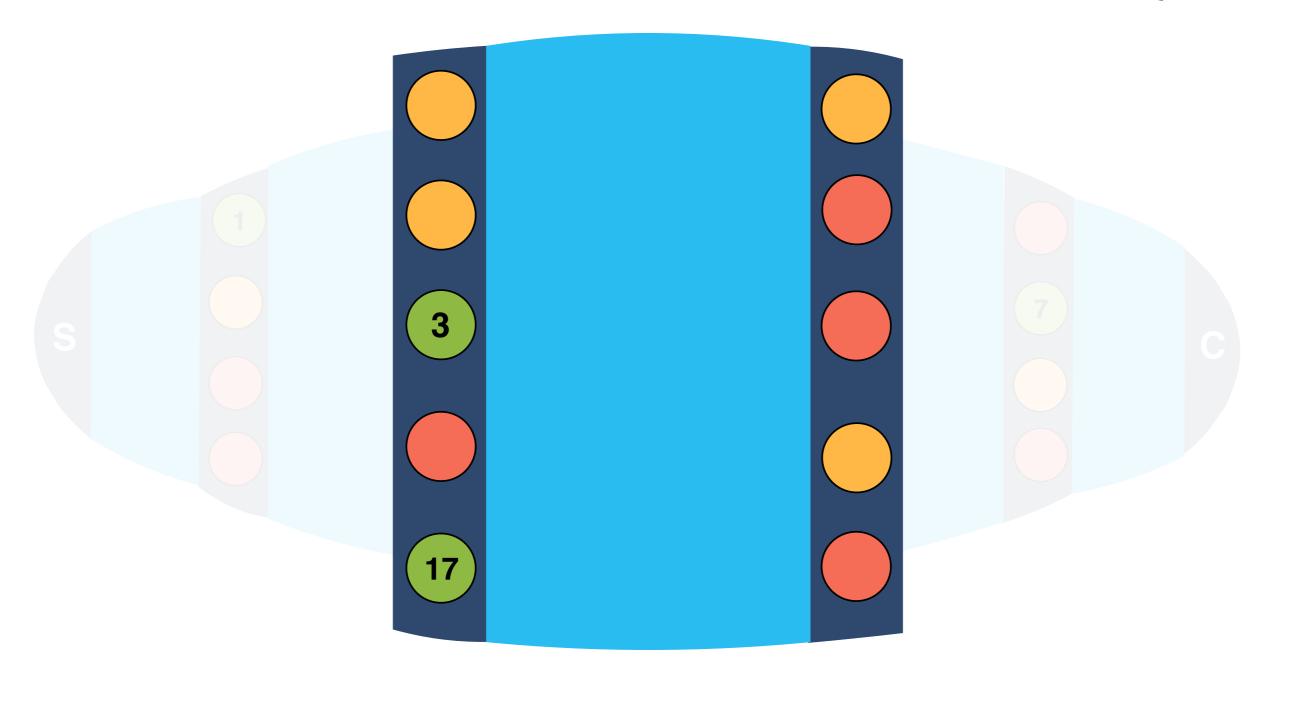
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The number of possible labelings = $(p + k + 1)^{pk} \le (3k)^{k^2} \le k^{(O(k^2))}$





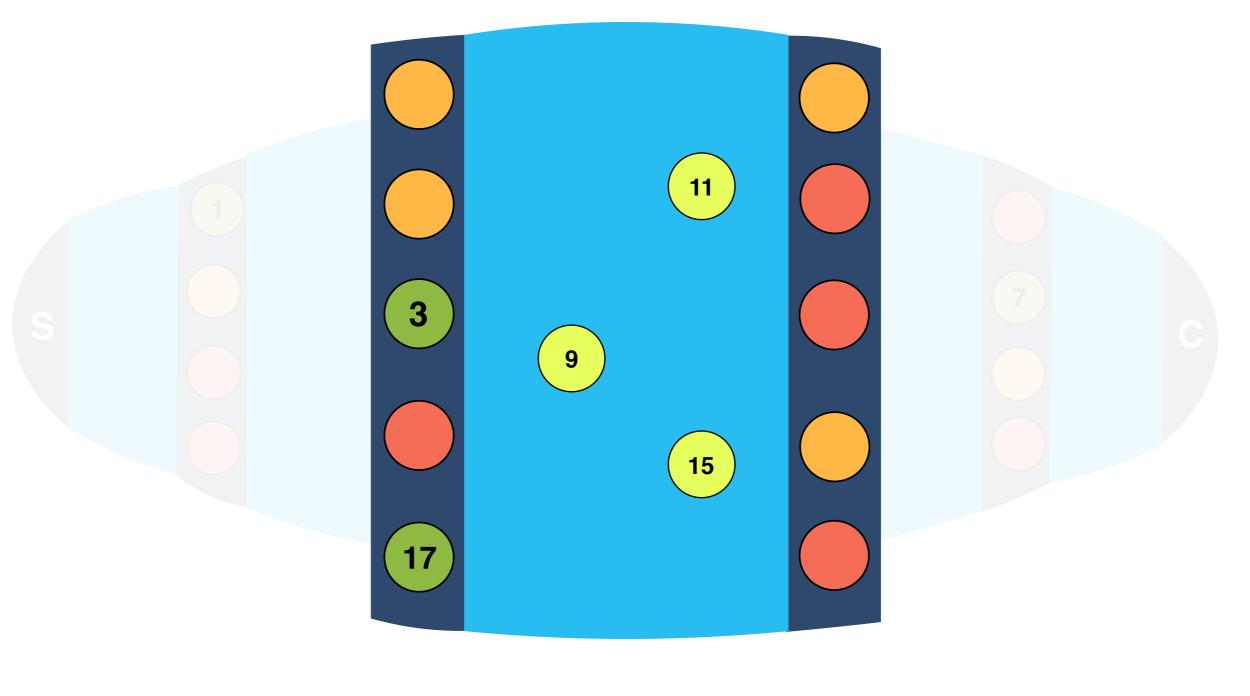


$$S_{i-1}$$

$$W_i$$

$$S_{i}$$

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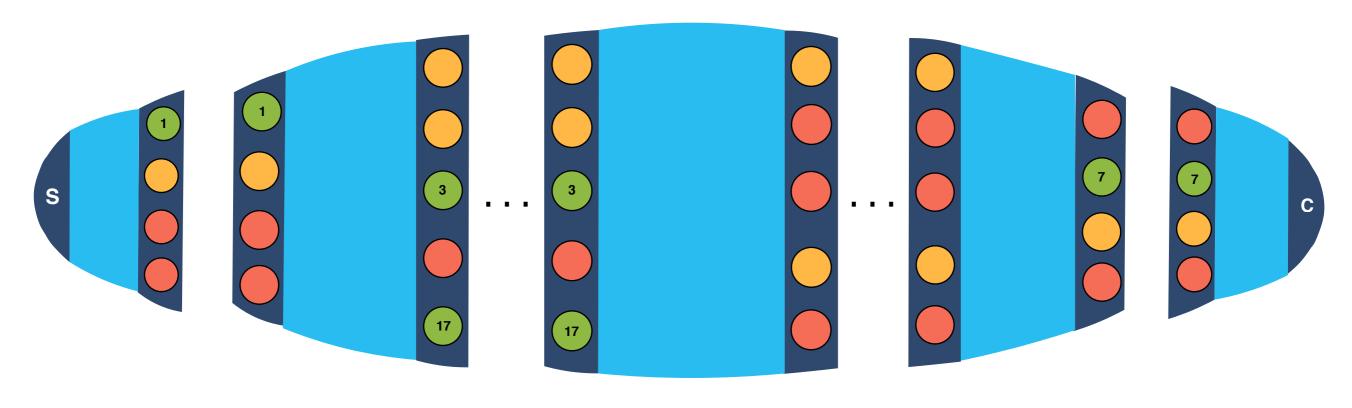
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Solving Recursively



$$G[S_1 \cup W_2 \cup S_2]$$

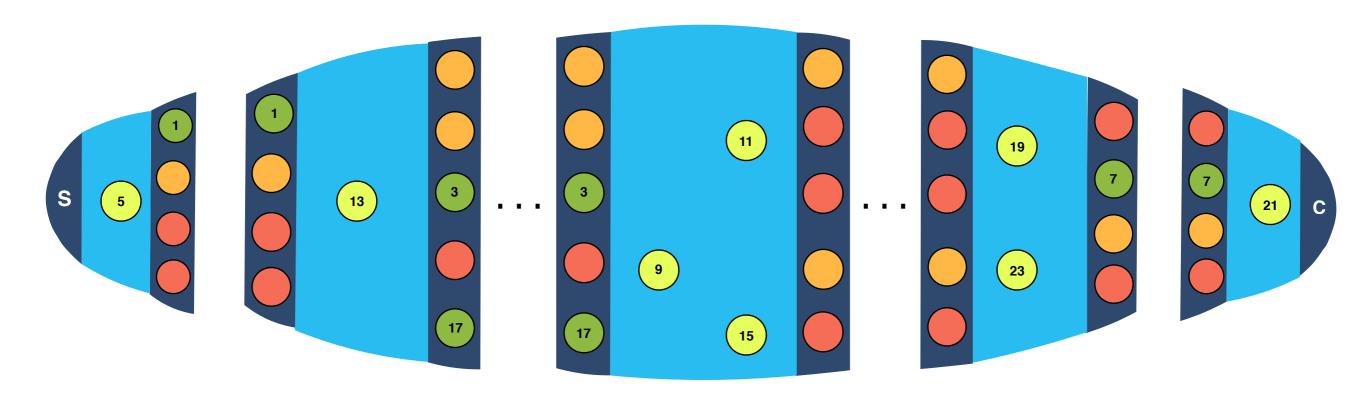
$$G[S_{i-1} \cup W_i \cup S_i]$$

$$G[S_{q-1} \cup W_q \cup S_q]$$

$$G[S_0 \cup W_1 \cup S_1]$$

$$G[S_q \cup W_{q+1} \cup S_{q+1}]$$

Solving Recursively



$$G[S_1 \cup W_2 \cup S_2]$$

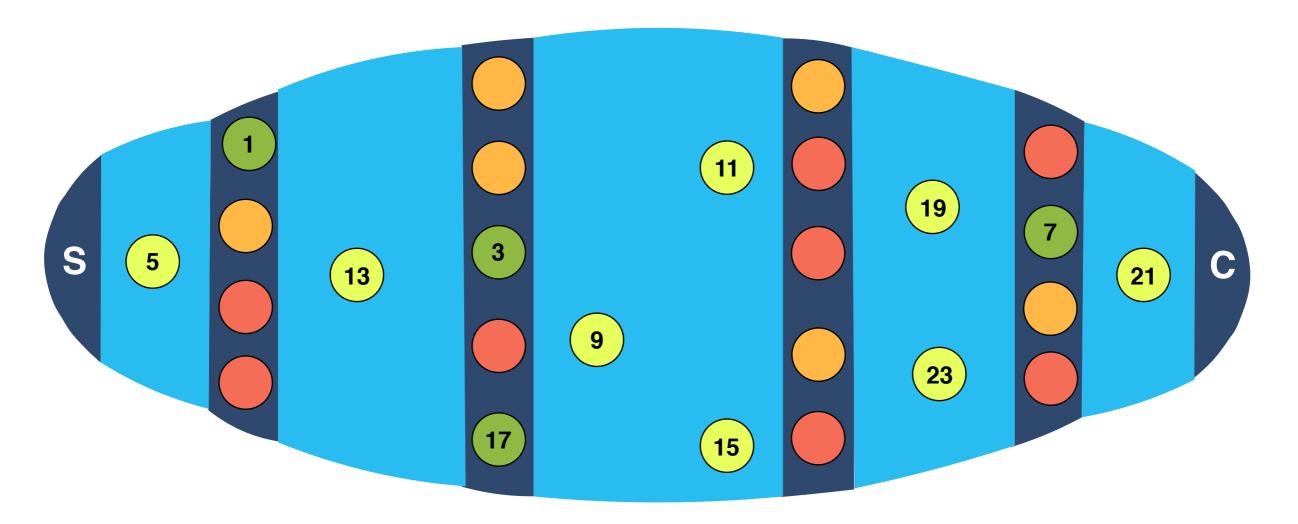
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$$G[S_q \cup W_{q+1} \cup S_{q+1}]$$

Combining the solutions



Algorithm

Algorithm 1: Solve-SACS-R(J) **Input**: An instance $(G, s, C, k, g, P, Q, Y, \gamma), p := |P|$ **Result**: YES if J is a YES-instance of SACS-R, and No otherwise. 1 **if** p = 0 and s and C are in different components of $G \setminus Y$ **then return** YES; 2 else return No; 3 **if** p > 0 and s and C are in different components of $G \setminus Y$ **then return** YES; 4 **if** there is no s - C separator of size at most p **then return** No; 5 Compute a tight s - C separator sequence S of order p. 6 **if** the number of separators in S is greater than k **then return** YES; 7 else **for** a non-trivial partition $T_1(P)$, $T_2(P)$ of P into 2q + 1 parts **do** 8 **for** a labeling \mathfrak{T} compatible with $\mathfrak{T}_1(P)$ **do** 9 if $\bigwedge_{i=1}^{q+1}$ (Solve-SACS-R($\Im(i, \Upsilon_1(P), \Upsilon_2(P), \mathfrak{T}_i)$)) then return Yes; 10

return No

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The Measure drops

Proposed measure is $\mu(G) = p$, which is the number of timestamps.

Claim: The quantity p always decrease when we recurse

Running Time

$$T(n, m, k, p) \le O(n^2 m p) + (p + k + 1)^{kp} \sum_{i=1}^{q+1} T(n_i, m_i, k, p_i)$$

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Recall that:

- each $p_i \leq k$,
- the depth of the recursion is bounded by p, and
- at the each level the work done is proportional to $k^{O(kp)}n^2m$

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Recall that:

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SACS is FPT and has an algorithm with running time $f(k)O(n^2m)$ where, $f(k) = k^{O(k^3)}$

Kernels on Trees

Kernelization

A kernelization algorithm, or simply a kernel, for a parameterized problem Q is an algorithm A that, given an instance (I,k) of Q, works in polynomial time and returns an equivalent instance (I',k'') of Q. Moreover, we require that $k' \le k$.

No Poly Kernels on Trees

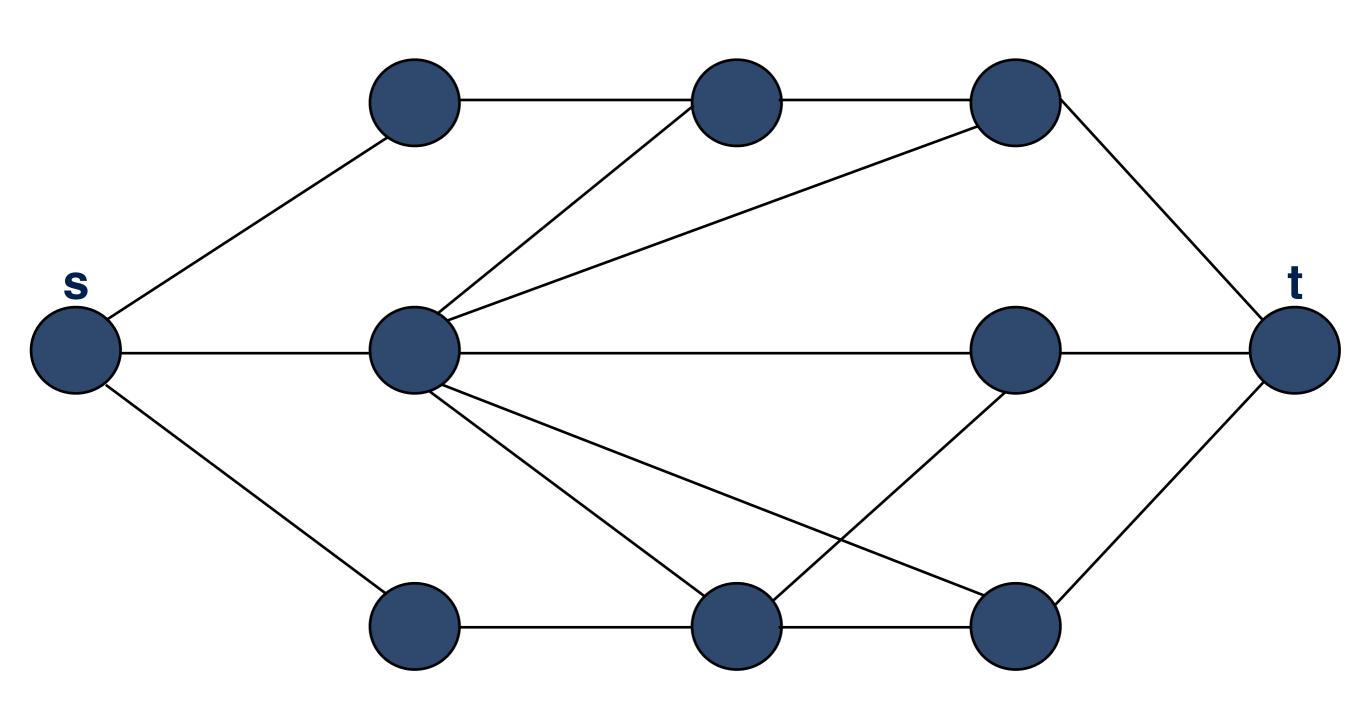
The unparameterized version of SACS restricted to trees cross composes to SACS restricted to trees when parameterized by the number of firefighters

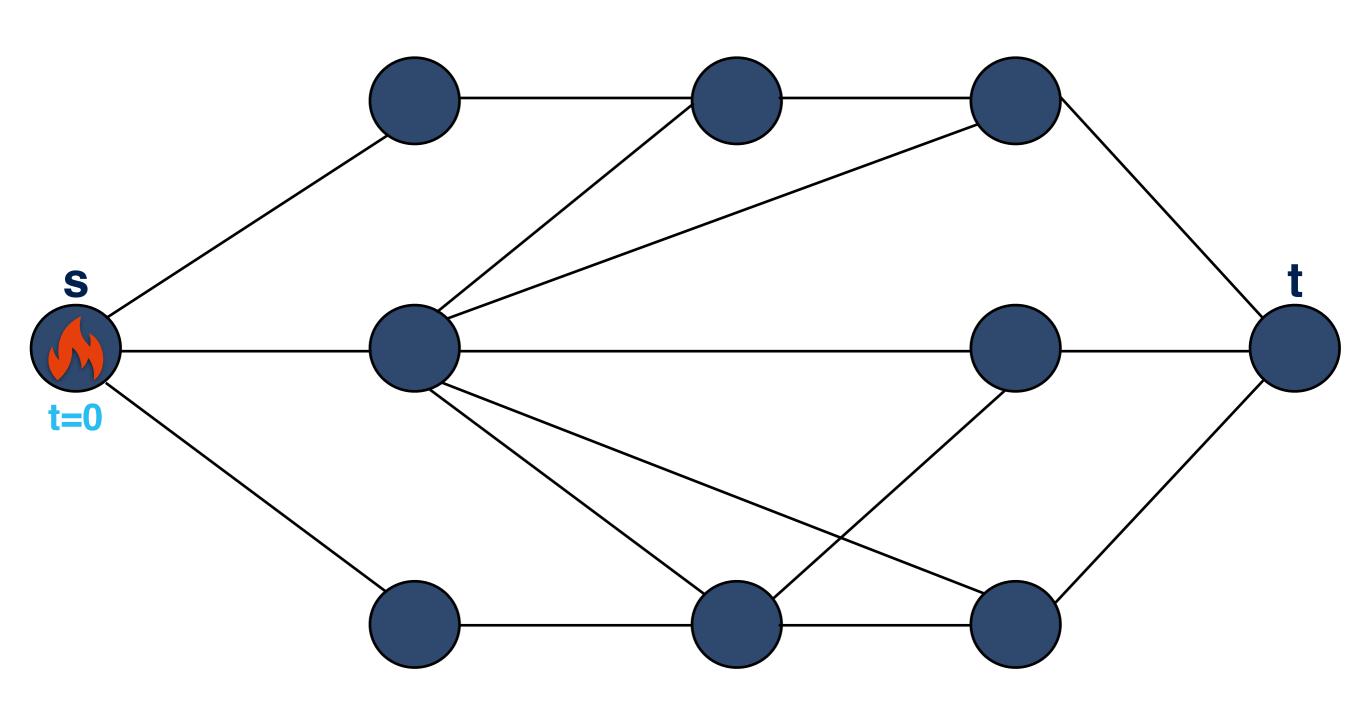
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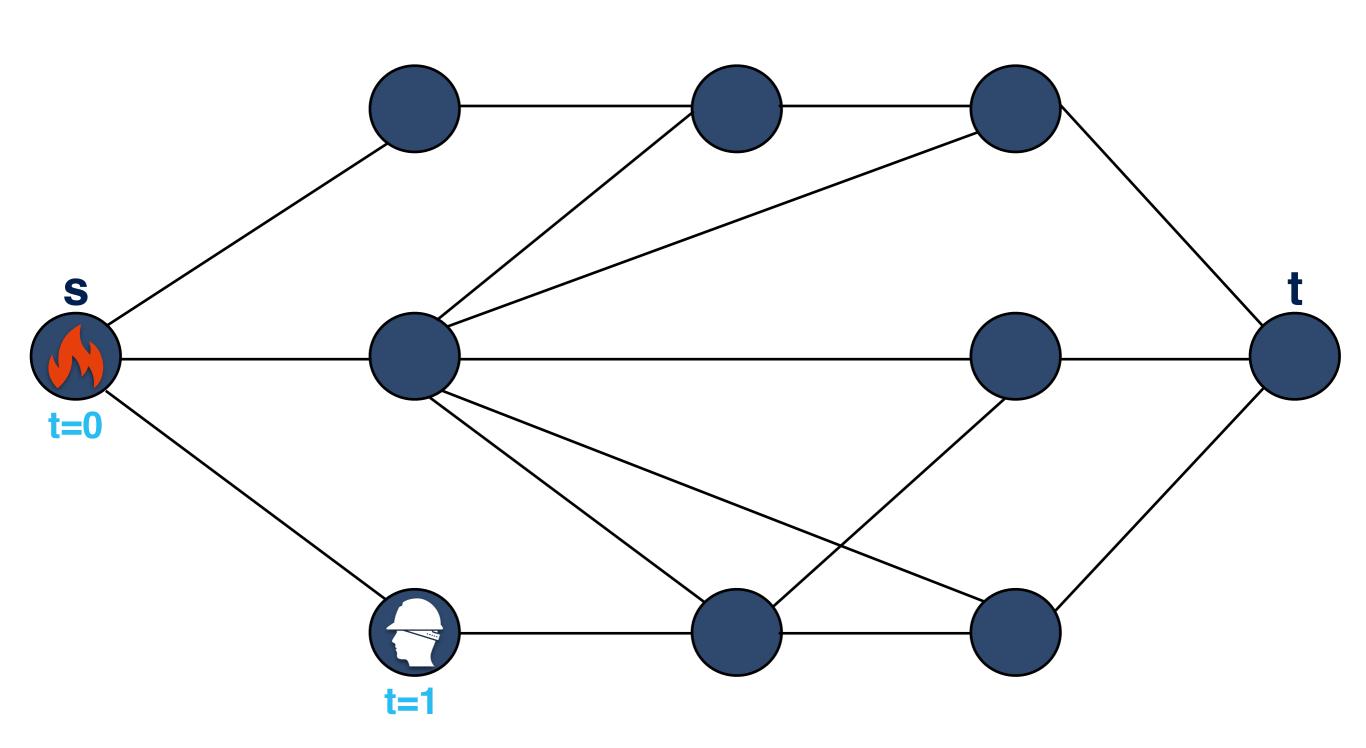
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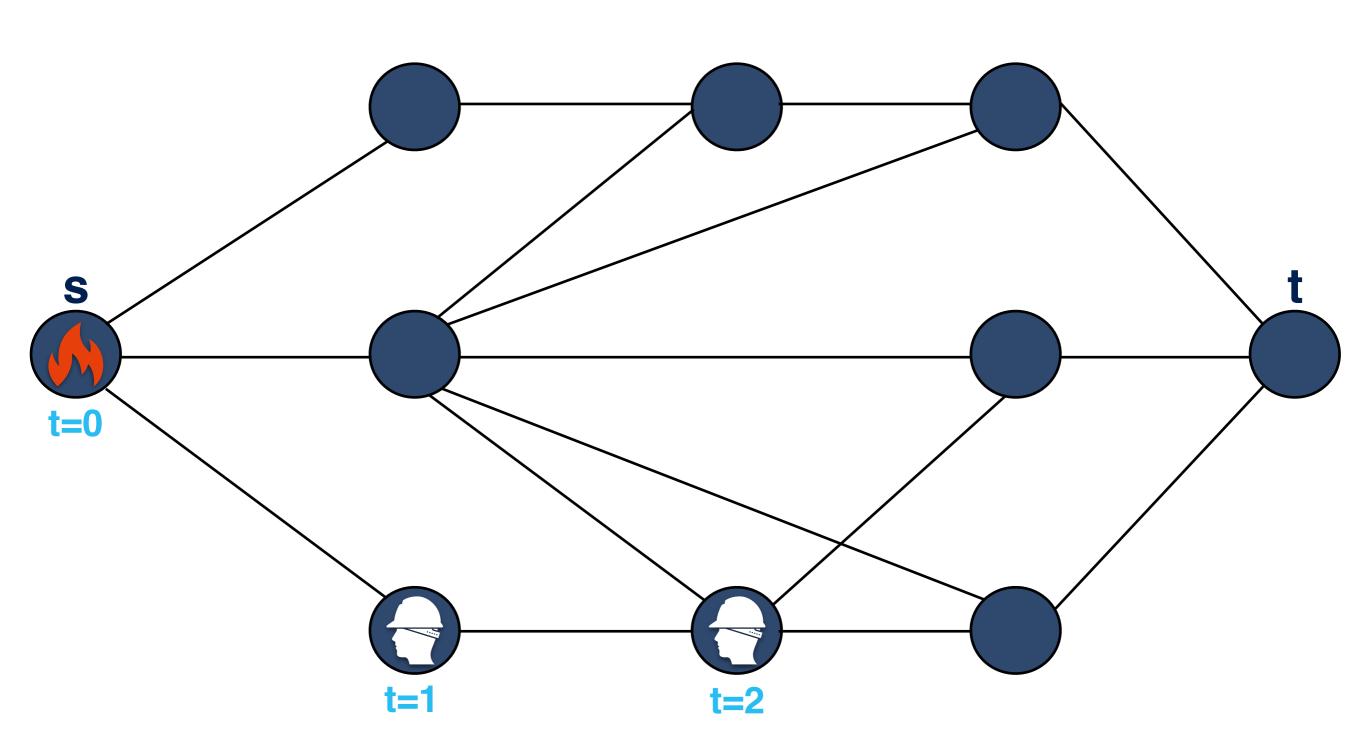
SACS when restricted to trees does not admit a polynomial kernel, unless $NP \subseteq coNP/poly$

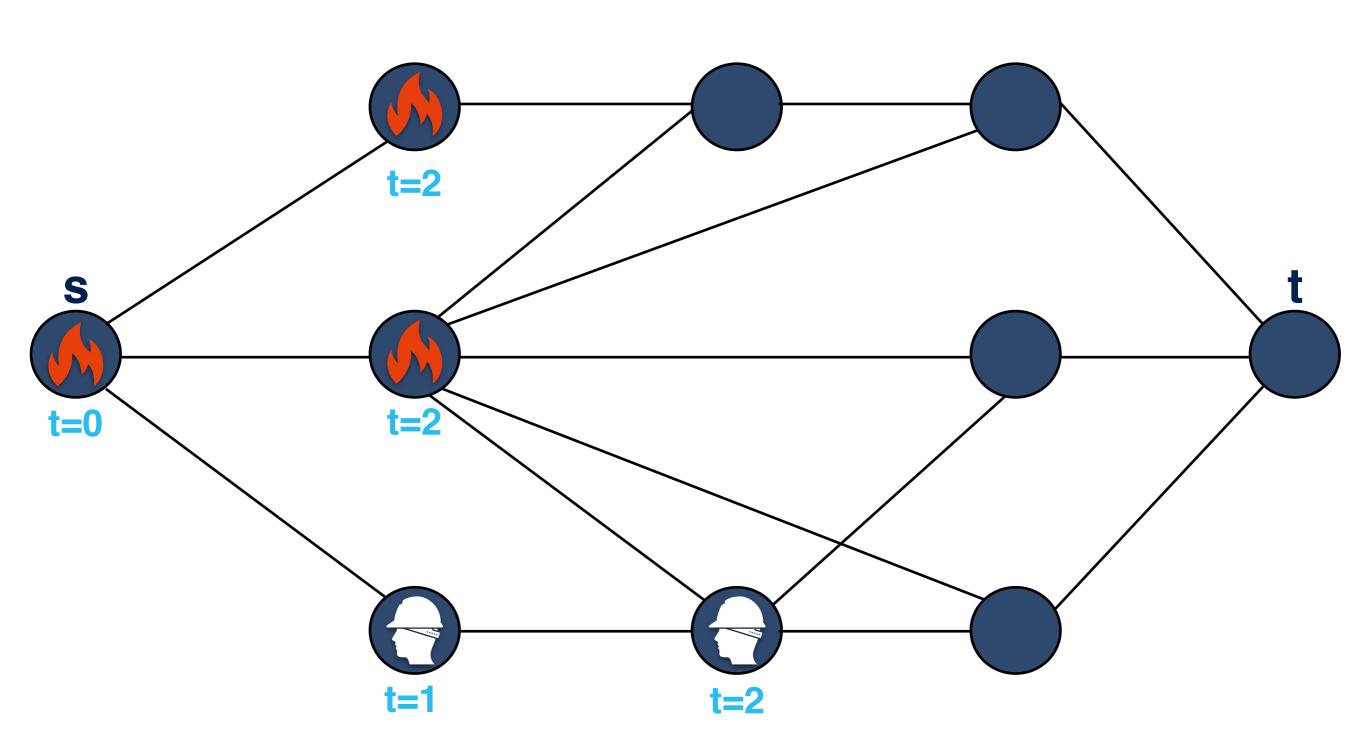
The Spreading Model

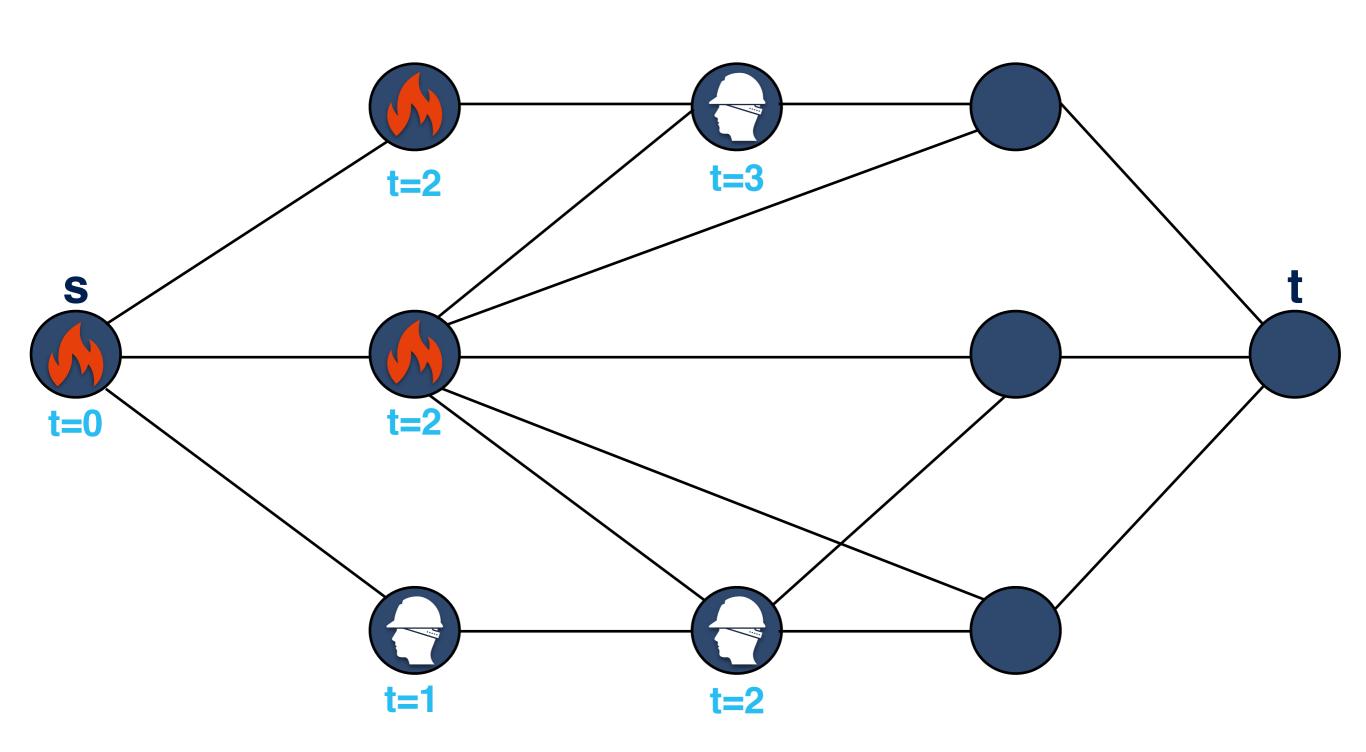


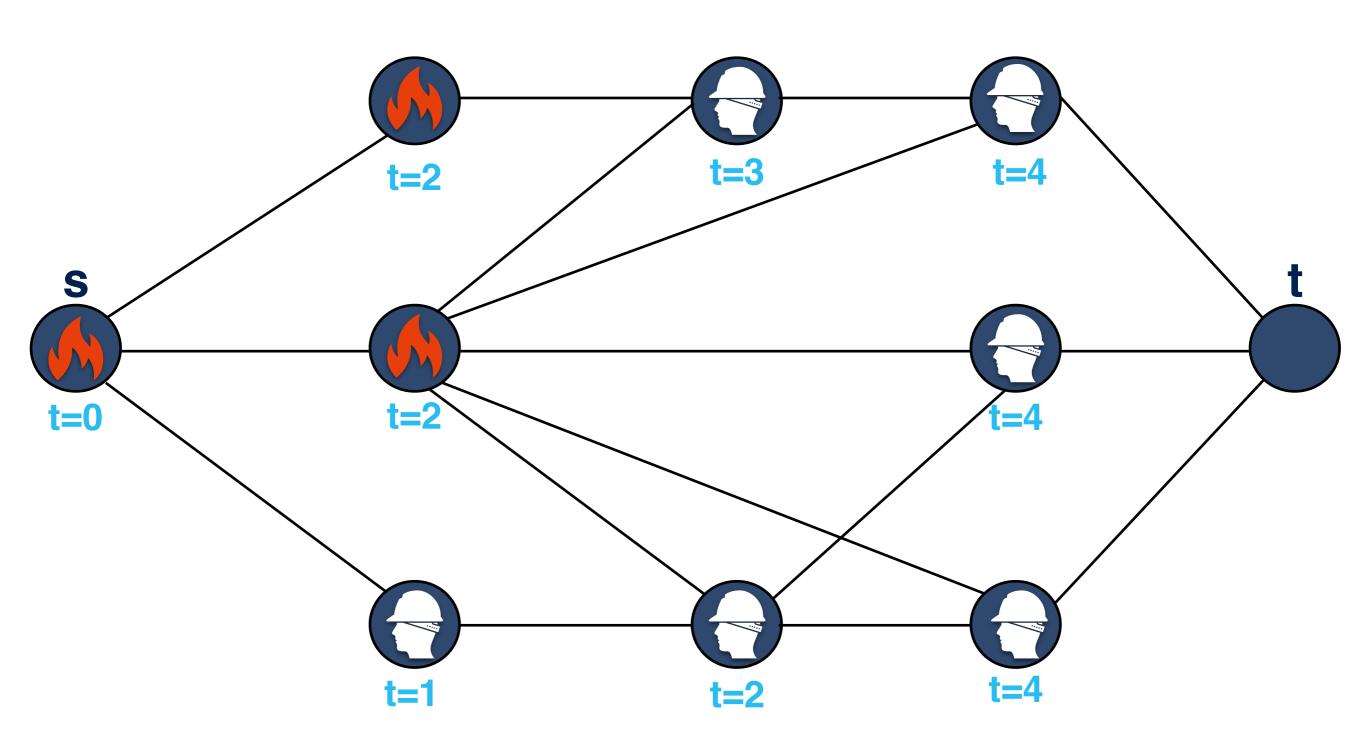












Theorem:

In the spreading model, SACS is as hard as k-DOMINATING SET

Conclusion

Conclusion and Future Work

- 1. Saving a Critical Set when parameterized by number of firefighters is FPT
- 2. There are no polynomial kernels for trees
- 3. In contrast to the general firefighting model, the spreading model is W[2]-Hard

4. Future Work:

- Kernels for graphs
- Smarter FPT algorithm
- Firefighting on graphs with bounded clique width, bounded clique-cover number, interval graphs, split graphs, permutation graphs, etc.

Questions?

Thank You